

Telegram Listing

Dx1000



Copyright

Copyright © 2017

SICK AG

Erwin-Sick-Str. 1

79183 Waldkirch

Germany

Table Of Contents

| | |
|--|-----------|
| 1 Preface..... | 6 |
| 1.1 About this document..... | 6 |
| 1.2 General..... | 6 |
| 1.3 IP configuration..... | 6 |
| 1.4 Minimum firmware revision..... | 6 |
| 1.5 Communication protocol CoLa A (ASCII telegram)..... | 6 |
| 1.6 Required user level..... | 6 |
| 1.7 Permanent saving of parameters..... | 7 |
| 1.8 Examples..... | 7 |
| 2 General..... | 9 |
| 2.1 Introduction..... | 9 |
| 2.2 User Level..... | 9 |
| 2.3 Methods..... | 9 |
| 2.4 Events..... | 9 |
| 2.5 Datatypes..... | 9 |
| 3 Interfaces..... | 11 |
| 3.1 Device Setup..... | 11 |
| 3.1.1 Measurement..... | 11 |
| 3.1.1.1 Basic Settings..... | 11 |
| 3.1.1.1.1 Variable: acquisitionTime [measurement cycle time]..... | 11 |
| 3.1.1.1.2 Variable: offset [distance offset]..... | 12 |
| 3.1.1.1.3 Variable: countingDirection [measuring direction]..... | 13 |
| 3.1.1.1.4 Variable: rainSnowFilterSetting [rain and snow filter]..... | 14 |
| 3.1.1.1.5 Variable: fogFilter [fog filter]..... | 15 |
| 3.1.1.2 Advanced Settings..... | 16 |
| 3.1.1.2.1 Variable: filterSelection [distance filter]..... | 16 |
| 3.1.1.2.2 Variable: filterDepth [Distance filter depth (of averaging filter)]..... | 17 |
| 3.1.1.2.3 Variable: echoSelectionMode [echo selection: first echo or last echo]..... | 18 |
| 3.1.1.2.4 Variable: roiStart [distance range: measuring range limit facing the device]..... | 19 |
| 3.1.1.2.5 Variable: roiEnd [distance range: measuring range limit facing away from the device]..... | 20 |
| 3.1.1.2.6 Variable: roiMinLevel [signal level range: lower signal level limit]..... | 21 |
| 3.1.1.2.7 Variable: roiMaxLevel [signal level range: upper signal level limit]..... | 22 |
| 3.1.1.2.8 Variable: noEchoOutputMode [substitute values for "no echo"] | 23 |
| 3.1.1.2.9 Variable: noEchoOutputDistance [user-defined substitute values: distance]..... | 24 |
| 3.1.1.2.10 Variable: noEchoOutputVelocity [user-defined substitute values: speed] | 25 |
| 3.1.1.2.11 Variable: errorOutputDistance [behaviour on error: user-defined substitute values: distance]..... | 26 |
| 3.1.1.2.12 Variable: errorOutputVelocity [behaviour on error: user-defined substitute values: speed] | 27 |
| 3.1.2 Interface..... | 28 |
| 3.1.2.1 Variable: preset [switching input: preset value]..... | 28 |
| 3.1.2.2 Variable: configIo1 [selection: In/Q1 as digital input or output]..... | 29 |
| 3.1.2.3 Variable: configIo2 [selection: QA/Q2 as analog input or digital output]..... | 30 |
| 3.1.2.4 Variable: configIo3 [selection: Q3 as digital output] | 31 |
| 3.1.2.5 Variable: configIo4 [selection: Q4 as digital output] | 32 |
| 3.1.2.6 Variable: configIo5 [selection: In2 as digital input] | 34 |
| 3.1.3 Device..... | 35 |
| 3.1.3.1 Laser..... | 35 |
| 3.1.3.1.1 Method: enableMeasurementLaser [switching the measurement laser on/off: on]..... | 35 |
| 3.1.3.1.2 Method: disableMeasurementLaser [Switching the measurement laser on/off: off]..... | 36 |
| 3.1.3.1.3 Method: enablePilotLaser [switching the alignment laser on/off: on] | 36 |
| 3.1.3.1.4 Method: disablePilotLaser [switching the alignment laser on/off: off] | 37 |

| | | |
|--------------|--|-----------|
| 3.1.3.2 | Heater..... | 38 |
| 3.1.3.2.1 | Variable: heaterSwitchingThreshold [switch-on temperature] | 38 |
| 3.1.3.2.2 | Method: switchHeaterOn [heating on]..... | 39 |
| 3.1.3.2.3 | Method: switchHeaterOff [heating off]..... | 39 |
| 3.1.3.2.4 | Method: switchHeaterAuto [auto: heating is activated if the measured temperature is below the defined switch-on temperature] | 40 |
| 3.1.3.3 | Display..... | 40 |
| 3.1.3.3.1 | Variable: displayContrast [display contrast]..... | 40 |
| 3.1.3.3.2 | Variable: displayBrightness [display brightness]..... | 41 |
| 3.1.3.3.3 | Variable: displayRotation [display orientation: 0° or 180°] | 42 |
| 3.1.3.3.4 | Variable: displayLanguage [language: English or German]..... | 43 |
| 3.1.3.4 | General | 44 |
| 3.1.3.4.1 | Method: resetParamAndReboot [factory settings: reset and reboot]..... | 44 |
| 3.1.4 | Communication..... | 44 |
| 3.1.4.1 | SSI | 44 |
| 3.1.4.1.1 | Variable: spdOutputMode [serial interface: select RS-422 or SSI]..... | 44 |
| 3.1.4.1.2 | Variable: serialOutputDistanceScale [distance value resolution for SSI data transfer: free input] | 45 |
| 3.1.4.1.3 | Variable: ssiProtocol [SSI coding] | 46 |
| 3.1.4.2 | RS422..... | 47 |
| 3.1.4.2.1 | Variable: spdOutputMode [serial interface: select RS-422 or SSI]..... | 47 |
| 3.1.4.2.2 | Variable: serialOutputDistanceScale [distance value resolution for RS-422 data transfer: free input] | 48 |
| 3.1.4.2.3 | Variable: serialOutputVelocityScale [speed value resolution for RS-422 data transfer: free input] | 49 |
| 3.1.4.2.4 | Variable: rs422PeriodicOutputContent [continuous RS-422 output] | 50 |
| 3.1.4.2.5 | Variable: rs422PeriodicOutputFormat [RS-422 data protocol]..... | 51 |
| 3.1.4.2.6 | Variable: rs422PeriodicDuration [RS-422 output cycle time] | 52 |
| 3.1.4.2.7 | Variable: rs422BaudRate [RS-422 data transmission rate] | 53 |
| 3.1.4.2.8 | Variable: rs422ByteFormat [RS-422 data format]..... | 54 |
| 3.1.5 | Info..... | 55 |
| 3.1.5.1 | Device | 55 |
| 3.1.5.1.1 | Variable: hwUpdateNumber [hardware revision of sensor]..... | 55 |
| 3.1.5.1.2 | Variable: productPartNo [part number of sensor]..... | 56 |
| 3.1.5.1.3 | Variable: SerialNumber [serial number of sensor]..... | 56 |
| 3.1.5.1.4 | Variable: productCode [product code/type of sensor] | 57 |
| 3.1.5.1.5 | Variable: interfaceVersion [interface revision]..... | 57 |
| 3.1.5.1.6 | Variable: firmwareBuildTime [Firmware: created on]..... | 58 |
| 3.1.5.1.7 | Variable: firmwareVerification [firmware verification]..... | 58 |
| 3.1.5.2 | I0s | 59 |
| 3.1.5.2.1 | Variable: eventCntIo1 [I0 counter: In1/Q1] | 59 |
| 3.1.5.2.2 | Variable: eventCntIo2 [I0 counter: Q2] | 60 |
| 3.1.5.2.3 | Variable: eventCntIo3 [I0 counter: Q3] | 60 |
| 3.1.5.2.4 | Variable: eventCntIo4 [I0 counter: Q4] | 61 |
| 3.1.5.2.5 | Variable: eventCntIo5 [I0 counter: In2] | 61 |
| 3.1.5.2.6 | Method: resetEventCounters [deleting the counter readings of switching events/reset] | 62 |
| 3.2 | Measurement | 63 |
| 3.2.1 | Variable: Distance [measured distance to object]..... | 63 |
| 3.2.2 | Variable: DistanceF [measured distance to object]..... | 63 |
| 3.2.3 | Variable: Velocity [measured object speed]..... | 64 |
| 3.2.4 | Variable: RSSI [measured signal level]..... | 64 |
| 3.2.5 | Variable: deviceTemperature [measured operating temperature of the device]..... | 65 |
| 3.2.6 | Variable: OpHoursDevice [operating time display] | 66 |
| 3.3 | Device Status Flags..... | 66 |
| 3.3.1 | Info..... | 66 |
| 3.3.1.1 | Variable: noEcho [bit 11 of status word: no echo]..... | 66 |
| 3.3.1.2 | Variable: BridgingActive [bit 12 of status word: no echo: delay time active]..... | 67 |
| 3.3.1.3 | Variable: laserState [bit 14 of status word: measurement laser active]..... | 68 |
| 3.3.1.4 | Variable: pilotState [bit 15 of status word: alignment laser active]..... | 68 |
| 3.3.1.5 | Variable: heaterStatus [bit 13 of status word: heating active] | 69 |
| 3.3.1.6 | Variable: io1state [bit 6 of status word: status (=switching state or input state) of Q1/In1]..... | 70 |
| 3.3.1.7 | Variable: io2state [bit 7 of status word: status (=switching state) of Q2]..... | 70 |
| 3.3.1.8 | Variable: io3state [bit 8 of status word: status (=switching state) of Q3]..... | 71 |

| | | |
|--------------|--|-----------|
| 3.3.1.9 | Variable: io4state [bit 9 of status word: status (=switching state) of Q4]..... | 71 |
| 3.3.1.10 | Variable: io5state [bit 10 of status word: status (= input state) of In2]..... | 72 |
| 3.3.1.11 | Variable: io1level [bit 1 of status word: level (= output or input potential) of Q1/In1]..... | 73 |
| 3.3.1.12 | Variable: io2level [bit 2 of status word: level (= output potential) of Q2]..... | 73 |
| 3.3.1.13 | Variable: io3level [bit 3 of status word: level (= output potential) of Q3]..... | 74 |
| 3.3.1.14 | Variable: io4level [bit 4 of status word: level (= output potential) of Q4]..... | 74 |
| 3.3.1.15 | Variable: io5level [bit 5 of status word: level (= input potential) of In2]..... | 75 |
| 3.3.1.16 | Variable: deviceStatusWord [device status word definition]..... | 76 |
| 3.3.2 | Error and Warning..... | 76 |
| 3.3.2.1 | Variable: laserError [bit 31 of status word: laser error] | 76 |
| 3.3.2.2 | Variable: hardwareFailure [bit 30 of status word: hardware error]..... | 77 |
| 3.3.2.3 | Variable: measurementError [bit 29 of status word: measurement error]..... | 77 |
| 3.3.2.4 | Variable: ambientLightError [bit 27 of status word: ambient light error]..... | 78 |
| 3.3.2.5 | Variable: temperatureError [bit 28 of status word: temperature error]..... | 79 |
| 3.3.2.6 | Variable: laserWarning [bit 23 of status word: warning: Laser]..... | 79 |
| 3.3.2.7 | Variable: firmwareWarning [bit 22 of status word: firmware warning]..... | 80 |
| 3.3.2.8 | Variable: ambientLightWarning [bit 19 of status word: warning: ambient light]..... | 80 |
| 3.3.2.9 | Variable: temperatureWarning [bit 20 of status word: warning: temperature] | 81 |
| 3.3.2.10 | Variable: doFault [bit 21 of status word: warning: shortcircuit at switching output] | 82 |
| 3.4 | Methods..... | 82 |
| 3.4.1 | General..... | 82 |
| 3.4.1.1 | Method: SetAccessMode | 82 |
| 3.4.1.2 | Method: Run | 83 |
| 3.4.1.3 | Method: resetParamAndReboot [reset and reboot]..... | 84 |
| 3.4.1.4 | Method: RebootDevice [reboot] | 84 |
| 3.4.2 | Preset..... | 85 |
| 3.4.2.1 | Method: autoZero [set output to 0] | 85 |
| 3.4.2.2 | Method: activatePreset [activate preset]..... | 85 |
| 3.4.2.3 | Method: resetPreset [delete preset value]..... | 86 |
| 4 | User Types..... | 87 |
| 4.1 | I0s | 87 |
| 4.1.1 | Type: ioConfiguration_t..... | 87 |
| 4.1.2 | Type: doFunction_t [assign monitoring function (distance, object speed or service) to digital output]..... | 87 |
| 4.1.3 | Type: distanceFunction_t [define switching function] | 88 |
| 4.1.4 | Type: movementDirection_t [defining the monitoring direction for the object speed value: positive (+) or Nnegative (-) or positive and negative (+/-)]..... | 88 |
| 4.1.5 | Type: diFunction_t [configuring the switching input: preset, alignment laser on, measurement laser off, deactivated]..... | 88 |
| 4.1.6 | Type: lowerSwitchPoint_t [switching function "distance to object": defining the switching point SP for distance value. Switching function "window": switching pointSP1]..... | 88 |
| 4.1.7 | Type: upperSwitchPoint_t [switching function "distance to object": NOT USED. Switching function "window": switching point SP2] | 89 |
| 4.1.8 | Type: distHysteresis_t [switching hysteresis for the distance value] | 89 |
| 4.1.9 | Type: veloSwitchpoint_t [switching point for the object speed value] | 89 |
| 4.1.10 | Type: veloHysteresis_t [switching point hysteresis for the object speed value] | 89 |
| 4.1.11 | Type: activeState_t [defining the active state] | 89 |
| 4.1.12 | Type: serviceFunctionState_t [Assigning a switching event to the service functions] | 90 |
| 5 | Appendix | 91 |
| 5.1 | Telegram structure: sFA ErrorCode | 91 |

1 Preface

1.1 About this document

Please read this document carefully before beginning to use the telegram listing. This document is an addendum to the operating instructions of the Dx1000 long range distance sensor. It describes the SICK protocol CoLa A (ASCII values) that is used to communicate with the long range distance sensor Dx1000.

Please note that the naming convention of parameters and variables in this document differs from the naming convention that is used in the sensor's operating manual, in SOPAS and in the sensor display (e.g., "acquisition time" vs. "measurement cycle time"). To facilitate navigation in this document, the chapter headings and the table of contents also contain the names of the parameters according to the sensor's operating manual in square brackets [].

1.2 General

The sensor's Ethernet interface allows setting sensor parameters as well as monitoring and controlling the sensor. Measured data such as distance or combined distance/speed values and operating data such as the internal temperature are transferred upon request. The Dx1000 Ethernet interface does not feature a continuous data output.

1.3 IP configuration

The devices generally support automatic IP address discovery. Default IP configuration:

- Static IP address
- IP address: 192.168.100.236
- IP subnet mask: 255.255.255.0
- Gateway address: 0.0.0.0
- TCP port: 2112

All variables and parameters that are available in the sensor display can be accessed through the Ethernet interface. The sensor can be remote controlled using the functions described herein.

1.4 Minimum firmware revision

This telegram listing is based on the following firmware revision: 1.5.0.0R

1.5 Communication protocol CoLa A (ASCII telegram)

The ASCII telegram has the advantage that commands can be written in plaintext. However, the string lengths of ASCII telegrams vary. The string consists only of two parts: the framing and the data part. The framing indicates with <STX> and <ETX> the start and stop of each telegram. The data part comprises the actual command with characters (plaintext), parameter values either in decimal or in hexadecimal and fixed hexadecimal values with a specific, intrinsic meaning. As leading zeros are being deleted, there is always a blank required between all command parts and parameter parts.

The length of the transmitted process data depends on their value. The process data are not complemented by leading zeros. Please refer to the syntax description in section 3. The maximum length is given by the datatype as indicated in the column "Type" and the column "Length [Byte]".

As further alternative within CoLa A, depending on the preferences of the user, all values can be written directly in Hex. This means however a 1:1 conversion of all characters and fixed hexadecimal values via the ASCII chart.

Negative values are represented in Hex by leading "F"s. Booleans are represented in HEX as 1 = TRUE and 0 = FALSE (please refer to the given examples below).

NOTE

The device will confirm parameter values always in hexadecimal code, regardless of the code sent.

1.6 Required user level

If device parameters need to be changed, the user must activate the access mode ("log in"). Changes become active when the access mode is set back to "Run" ("log out"). It is mandatory to perform a log in/log out sequence for each parameter change. I.e., after log in, only one parameter is to be amended, immediately followed by log out. The examples listed in section 1.8 describe the log in using the default password "81BE23AA". This is the hash value of the password at the time of delivery ("servicelevel") for the user level "Service". If the password has been changed through SOPAS ET, the respective hash value must be entered there.

1.7 Permanent saving of parameters

Permanent saving of changed parameters requires executing a special command; see "Special functions" in the operating instructions of the Dx1000 and in this document.

1.8 Examples

This chapter provides frequently used examples how to read out variables from the sensor and how to set parameters.

Example 1: Log in at user level "Service"

Request: <STX>sMN SetAccessMode 4 81BE23AA<ETX>
Response: <STX>sAN SetAccessMode 1<ETX>

Syntax of "Log in" request in greater detail:

| | | | | |
|-------|--|-------|--|-------------------------------------|
| ASCII | | <STX> | sMN{SPC}SetAccessMode{SPC}4{SPC}81BE23AA | <ETX> |
| Hex | | 02 | 73 4D 4E 20 53 65 74 41 63 63 65 73 73 4D 6F 64 65 | 20 34 20 38 31 42 45 32 33 41 41 03 |

- Framing = <STX> = telegram start
- Data:
 - sMN = start of SOPAS command (and blank)
 - SetAccessMode = the actual command for setting the user level (and blank)
 - 4 = value meaning user level "Service" (and blank)
 - 81BE23AA = Hash value of the password at the time of delivery ("servicelevel") for the user level "Service". If the password has been changed through SOPAS ET, the respective hash value must be entered here.
- Framing = <ETX> = telegram stop

See also "3.4.1.1 Method: SetAccessMode" on page 82.

Example 2: Read out the distance value (here 1489mm)

Request: <STX>sRN Distance<ETX>
Response: <STX>sRA Distance 5D1<ETX>

See also "3.2.1 Variable: Distance" on page 63.

Example 3: Read out the measured object speed (here 510mm/s)

Request: <STX>sRN Velocity<ETX>
Response: <STX>sRA Velocity 1FE<ETX>

See also "3.2.3 Variable: Velocity" on page 64.

Example 4: Read out the (negative) distance value and the object speed (here -3276mm and 291mm/s, respectively)

Request: <STX>sRN Distance<ETX>
Response: <STX>sRA Distance FFFF334<ETX>

Request: <STX>sRN Velocity<ETX>
Response: <STX>sRA Velocity 123<ETX>

See also "3.2.1 Variable: Distance" on page 63 and "3.2.3 Variable: Velocity [measured object speed]" on page 64.

Example 5: Read out the device temperature (here -1 ° C)

Request: <STX>sRN deviceTemperature<ETX>
Response: <STX>sRA deviceTemperature FF<ETX>

See also "3.2.5 Variable: deviceTemperature" on page 65.

Example 6: Read out state of measurement laser (1 = measurement laser is on)

Request: <STX>sRN laserState<ETX>
Response: <STX>sRA laserState 1<ETX>

See also "3.3.1.3 Variable: laserState" on page 68.

Example 7: Read out the deviceStatusWord

Request: <STX>sRN deviceStatusWord<ETX>
Response: <STX>sRA deviceStatusWord 0<ETX>

See also "3.3.1.16 Variable: deviceStatusWord" on page 76.

Example 8: Read out laserError (1 = Error)

Request: <STX>sRN laserError<ETX>
Response: <STX>sRA laserError 1<ETX>

See also “3.3.2.1 Variable: laserError” on page 76.

Example 9: Defining the echo selection: Last echo

Log in: <STX>sMN SetAccessMode 4 81BE23AA<ETX>
Response: <STX>sAN SetAccessMode 1<ETX>
Request: <STX>sWN echoSeletionMode 1<ETX>
Response: <STX>sWA echoSeletionMode<ETX>
Log out: <STX>sMN Run<ETX>
Response: <STX>sAN Run 1<ETX>

See also “3.1.1.2.3 Variable: echoSeletionMode [echo selection: first echo or last echo]” on page 18, “3.4.1.1 Method: SetAccessMode” on page 82 and “3.4.1.2 Method: Run” on page 83.

Example 10: Configuring the distance range: Set upper measuring range limit to 30 m

Log in: <STX>sMN SetAccessMode 4 81BE23AA<ETX>
Response: <STX>sAN SetAccessMode 1<ETX>
Request: <STX>sWN roiEnd 30000<ETX>
Response: <STX>sWA roiEnd<ETX>
Log out: <STX>sMN Run<ETX>
Response: <STX>sAN Run 1<ETX>

See also “3.1.1.2.5 Variable: roiEnd [distance range: measuring range limit facing away from the device]” on page 20, “3.4.1.1 Method: SetAccessMode” on page 82 and “3.4.1.2 Method: Run” on page 83.

2 General

2.1 Introduction

This document describes the functional interfaces of the Dx1000 device, 1.5.0.0R. The Dx1000 device is a SOPAS device. SOPAS devices have Variables, Methods and Events. Variables can always be read and in some cases be written by user.

2.2 User Level

Whether a Variable can be written by user depends on the least user level. Defined user levels are:

| ID | Name |
|----|-------------------|
| 0 | Always (Run) |
| 1 | Operator |
| 2 | Maintenance |
| 3 | Authorised Client |
| 4 | Service |

2.3 Methods

Methods can be invoked by using certain parameters. The method will return with a structure of one or more return values. If a Method can be invoked depends as well on the least user level (see above).

2.4 Events

Events can be registered and will then be fired by the device to the registered client. Most Events have parameters which are the data coming with the Event.

2.5 Datatypes

All items of the interface have certain data elements. These are the Variables itself, the parameters of Methods and Events and the return values of the Methods.

The structure of the data elements can be one of the following BasicType(s), Structures or Arrays.

Basic Type

| Name | Description | Range of values |
|------------|--|---|
| Bool | boolean | True(1), False(0) |
| USInt | unsigned short (8 bit) | (0..255) |
| UInt | unsigned int (16 bit) | (0..65535) |
| UDInt | unsigned double int (32 bit) | (0..4294967295) |
| ULInt | unsigned long int (64 bit) | (0..18446744073709551616) |
| SInt | signed short (8 bit) | (-128..127) |
| Int | signed int (16 bit) | (-32768..32767) |
| DInt | signed double int (32 bit) | (-2147483648..2147483647) |
| LInt | signed long int (64 bit) | (-9223372036854775808..9223372036854775807) |
| Real | IEEE-754 single precision (32 bit) (float) | See specification in IEEE-754 |
| LReal | IEEE-754 single precision (64 bit) (double) | See specification in IEEE-754 |
| Enum8 | short enumeration (8 bit) | certain values defined in a list of choices (0-255) |
| Enum16 | short enumeration (16 bit) | certain values defined in a list of choices (0-65535) |
| String | array of visible characters (array of 8 bit) | a character = an USInt with values between 0x20..0xFF |
| FlexString | array of visible characters with preceding current length (UInt length) (array of 8 bit) | See description of String and FlexArray |

| Name | Description | Range of values |
|-------|---|---|
| Byte | bitset definition (8 bit). Detailed specification of bits UInt1..UInt16 = UInt (1..16 bit) Int1..Int16 = Int (1..16 bit) Enum1..Enum16 = Enum16 (1..16 bit) Bool = Bool (1 bit) | value is transferred as an array of USInt. See "XByte Serialisation" document for further details on bit ordering |
| Word | bitset definition (16 bit), see description of Byte | value is transferred as an array of USInt see "XByte Serialisation" document for further details on bit ordering. |
| DWord | bitset definition (32 bit), see description of Byte | value is transferred as an array of USInt see "XByte Serialisation" document for further details on bit ordering. |
| LWord | bitset definition (64 bit), see description of Byte | value is transferred as an array of USInt see "XByte Serialisation" document for further details on bit ordering. |
| XByte | bitset definition (8,16,24,32,... bit) see description of Byte | value is transferred as an array of USInt see "XByte Serialisation" document for further details on bit ordering. |
| SCont | bitset definition (8 bit). Detailed specification of bits UInt1..UInt16 = UInt (1..16 bit) Int1..Int16 = Int (1..16 bit) Enum1..Enum16 = Enum16 (1..16 bit) Bool = Bool (1 bit) | value is transferred as USInt. |
| Cont | bitset definition (16 bit), see description of SCont | value is transferred as UInt. |
| DCont | bitset definition (32 bit), see description of SCont | value is transferred as UDInt. |
| LCont | bitset definition (64 bit), see description of SCont | value is transferred as UILInt. |

Struct

A structure is a sequence of further types. These types can be of a BasicType, Structs again or an Array.

Array

An Array is a repetition of a type. The length of the array is defined with each Array. The types can be of a BasicType, a Struct or an Array again (n- dimensional).

Flex Array

A FlexArray is a repetition of a type with a variable length. The maximum length of the array is defined with each FlexArray. The current length of the FlexArray is transferred as a UInt preceding the Array itself. The types can be of a BasicType, a Struct or an Array again (n- dimensional).

3 Interfaces

3.1 Device Setup

3.1.1 Measurement

3.1.1.1 Basic Settings

3.1.1.1.1 Variable: acquisitionTime [measurement cycle time]

The following section contains a detailed description of the variable acquisitionTime.

Variable Overview

| Variable Name | Description | | |
|-----------------|---------------------------|-------------|--|
| acquisitionTime | Acquisition Time | | |
| Read-Access | AuthorizedClient, Service | | |
| Write-Access | AuthorizedClient, Service | | |
| Enum8 | | | |
| Default Value | s4_MS | | |
| Value | Name | Description | |
| 0 | s1_MS | | |
| 1 | s4_MS | | |
| 2 | s16_MS | | |
| 3 | s64_MS | | |
| 4 | s128_MS | | |

Variable Telegram Syntax

Read Variable:

sRN acquisitionTime

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | acquisitionTime | String | 15 | Acquisition Time |

Read Variable Response:

sRA acquisitionTime <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------------|--------|---------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | acquisitionTime | String | 15 | Acquisition Time |
| Variable Data | data | Enum8 | 1 | |

Write Variable:

sWN acquisitionTime <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------------|--------|---------------|------------------------------|
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | acquisitionTime | String | 15 | Acquisition Time |
| Variable Data | data | Enum8 | 1 | |

Write Variable Response:

sWA acquisitionTime

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------------|--------|---------------|----------------------------------|
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | acquisitionTime | String | 15 | Acquisition Time |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|---------------------------------|---------------------------------|
| Read Variable: | [STX]sRN acquisitionTime[ETX] |
| Read Variable Response: | [STX]sRA acquisitionTime 1[ETX] |
| Write Variable: | [STX]sWN acquisitionTime 1[ETX] |
| Write Variable Response: | [STX]sWA acquisitionTime[ETX] |

3.1.1.1.2 Variable: offset [distance offset]

The following section contains a detailed description of the variable offset.

Variable Overview

| Variable Name | Description |
|----------------|---------------------------|
| offset | Offset in mm |
| Read-Access | Always |
| Write-Access | AuthorizedClient, Service |
| DInt | |
| Value Range | -4500000..4500000 |
| Initialisation | 0 |

Variable Telegram Syntax

Read Variable:

sRN offset

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | offset | String | 6 | Offset in mm |

Read Variable Response:

sRA offset <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------|--------|---------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | offset | String | 6 | Offset in mm |
| Variable Data | data | DInt | 4 | |

Write Variable:

sWN offset <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------|--------|---------------|------------------------------|
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | offset | String | 6 | Offset in mm |
| Variable Data | data | DInt | 4 | |

Write Variable Response:

sWA offset

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------|--------|---------------|----------------------------------|
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | offset | String | 6 | Offset in mm |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|---------------------------------|------------------------|
| Read Variable: | [STX]sRN offset[ETX] |
| Read Variable Response: | [STX]sRA offset 0[ETX] |
| Write Variable: | [STX]sWN offset 0[ETX] |
| Write Variable Response: | [STX]sWA offset[ETX] |

3.1.1.1.3 Variable: countingDirection [measuring direction]

The following section contains a detailed description of the variable countingDirection.

Variable Overview

| Variable Name | Description | |
|-------------------|---|-------------|
| countingDirection | Counting Direction can be either positive or negative | |
| Read-Access | Always | |
| Write-Access | AuthorizedClient, Service | |
| Enum8 | | |
| Default Value | POSITIVE | |
| Value | Name | Description |
| 0 | POSITIVE | |
| 1 | NEGATIVE | |

Variable Telegram Syntax

Read Variable:

sRN countingDirection

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-------------------|--------|---------------|---|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | countingDirection | String | 17 | Counting Direction can be either positive or negative |

Read Variable Response:

sRA countingDirection <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-------------------|--------|---------------|---|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | countingDirection | String | 17 | Counting Direction can be either positive or negative |
| Variable Data | data | Enum8 | 1 | |

Write Variable:

sWN countingDirection <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-------------------|--------|---------------|---|
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | countingDirection | String | 17 | Counting Direction can be either positive or negative |
| Variable Data | data | Enum8 | 1 | |

Write Variable Response:

sWA countingDirection

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-------------------|--------|---------------|---|
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | countingDirection | String | 17 | Counting Direction can be either positive or negative |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|--------------------------|-----------------------------------|
| Read Variable: | [STX]sRN countingDirection[ETX] |
| Read Variable Response: | [STX]sRA countingDirection 0[ETX] |
| Write Variable: | [STX]sWN countingDirection 0[ETX] |
| Write Variable Response: | [STX]sWA countingDirection[ETX] |

3.1.1.1.4 Variable: rainSnowFilterSetting [rain and snow filter]

The following section contains a detailed description of the variable rainSnowFilterSetting.

Variable Overview

| Variable Name | Description |
|-----------------------|---|
| rainSnowFilterSetting | Rain Snow Median (how often has an echo to occur before it is accepted) |
| Read-Access | Always |
| Write-Access | AuthorizedClient, Service |

Enum8

| | | |
|---------------|-----------|-------------|
| Default Value | s9_of_16 | |
| Value | Name | Description |
| 0 | s1_of_1 | |
| 1 | s5_of_8 | |
| 2 | s9_of_16 | |
| 3 | s13_of_23 | |
| 4 | s17_of_32 | |

Variable Telegram Syntax

Read Variable:

sRN rainSnowFilterSetting

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------------------|--------|---------------|---|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | rainSnowFilterSetting | String | 21 | Rain Snow Median (how often has an echo to occur before it is accepted) |

Read Variable Response:

sRA rainSnowFilterSetting <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------------------|--------|---------------|---|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | rainSnowFilterSetting | String | 21 | Rain Snow Median (how often has an echo to occur before it is accepted) |
| Variable Data | data | Enum8 | 1 | |

Write Variable:

sWN rainSnowFilterSetting <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------------------|--------|---------------|---|
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | rainSnowFilterSetting | String | 21 | Rain Snow Median (how often has an echo to occur before it is accepted) |
| Variable Data | data | Enum8 | 1 | |

Write Variable Response:

sWA rainSnowFilterSetting

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------|--------|---------------|----------------------------------|
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |

Write Variable Response:

sWA rainSnowFilterSetting

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------------------|--------|---------------|---|
| Command | rainSnowFilterSetting | String | 21 | Rain Snow Median (how often has an echo to occur before it is accepted) |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|---------------------------------|---------------------------------------|
| Read Variable: | [STX]sRN_rainSnowFilterSetting[ETX] |
| Read Variable Response: | [STX]sRA_rainSnowFilterSetting 2[ETX] |
| Write Variable: | [STX]sWN_rainSnowFilterSetting 2[ETX] |
| Write Variable Response: | [STX]sWA_rainSnowFilterSetting[ETX] |

3.1.1.1.5 Variable: fogFilter [fog filter]

The following section contains a detailed description of the variable fogFilter.

Variable Overview

| Variable Name | Description |
|---------------|-------------|
| fogFilter | Fog Filter |

| | |
|--------------|---------------------------|
| Read-Access | Always |
| Write-Access | AuthorizedClient, Service |

| Enum8 | | | |
|---------------|------|-------------|--|
| Default Value | ON | | |
| Value | Name | Description | |
| 0 | OFF | | |
| 1 | ON | | |

Variable Telegram Syntax

Read Variable:

sRN_fogFilter

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | fogFilter | String | 9 | Fog Filter |

Read Variable Response:

sRA_fogFilter <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------|--------|---------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | fogFilter | String | 9 | Fog Filter |
| Variable Data | data | Enum8 | 1 | |

Write Variable:

sWN_fogFilter <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------|--------|---------------|------------------------------|
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | fogFilter | String | 9 | Fog Filter |
| Variable Data | data | Enum8 | 1 | |

Write Variable Response:

sWA_fogFilter

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------|--------|---------------|----------------------------------|
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | fogFilter | String | 9 | Fog Filter |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|---------------------------------|---------------------------|
| Read Variable: | [STX]sRN_fogFilter[ETX] |
| Read Variable Response: | [STX]sRA_fogFilter 1[ETX] |
| Write Variable: | [STX]sWN_fogFilter 1[ETX] |
| Write Variable Response: | [STX]sWA_fogFilter[ETX] |

3.1.1.2 Advanced Settings

3.1.1.2.1 Variable: filterSelection [distance filter]

The following section contains a detailed description of the variable filterSelection.

Variable Overview

| Variable Name | Description | |
|-----------------|---|-----------------------------|
| filterSelection | Suppress sporadic echos that overlapp the true echo | |
| Read-Access | Always | |
| Write-Access | AuthorizedClient, Service | |
| Enum8 | | |
| Default Value | KALMAN | |
| Value | Name | Description |
| 0 | MEAN | Apply moving average filter |
| 1 | KALMAN | Apply Kalman filter |

Variable Telegram Syntax

| Read Variable: | | | | |
|----------------------------|-----------------|--------|---------------|---|
| sRN filterSelection | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | filterSelection | String | 15 | Suppress sporadic echos that overlapp the true echo |
| Read Variable Response: | | | | |
| sRA filterSelection <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | filterSelection | String | 15 | Suppress sporadic echos that overlapp the true echo |
| Variable Data | data | Enum8 | 1 | |
| Write Variable: | | | | |
| sWN filterSelection <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | filterSelection | String | 15 | Suppress sporadic echos that overlapp the true echo |
| Variable Data | data | Enum8 | 1 | |
| Write Variable Response: | | | | |
| sWA filterSelection | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Write Variable Response: | | | | |
| sWA filterSelection | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command | filterSelection | String | 15 | Suppress sporadic echos that overlapp the true echo |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|---------------------------------|---------------------------------|
| Read Variable: | [STX]sRN filterSelection[ETX] |
| Read Variable Response: | [STX]sRA filterSelection 1[ETX] |
| Write Variable: | [STX]sWN filterSelection 1[ETX] |
| Write Variable Response: | [STX]sWA filterSelection[ETX] |

3.1.1.2.2 Variable: filterDepth [Distance filter depth (of averaging filter)]

The following section contains a detailed description of the variable filterDepth.

Variable Overview

| Variable Name | Description |
|----------------|---------------------------|
| filterDepth | Filter depth in steps |
| Read-Access | Always |
| Write-Access | AuthorizedClient, Service |
| UDInt | |
| Value Range | 1..1023 |
| Initialisation | 1 |

Variable Telegram Syntax

Read Variable:

sRN filterDepth

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-------------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | filterDepth | String | 11 | Filter depth in steps |

Read Variable Response:

sRA filterDepth <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-------------|--------|---------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | filterDepth | String | 11 | Filter depth in steps |
| Variable Data | data | UDInt | 4 | |

Write Variable:

sWN filterDepth <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-------------|--------|---------------|------------------------------|
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | filterDepth | String | 11 | Filter depth in steps |
| Variable Data | data | UDInt | 4 | |

Write Variable Response:

sWA filterDepth

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-------------|--------|---------------|----------------------------------|
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | filterDepth | String | 11 | Filter depth in steps |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|---------------------------------|-----------------------------|
| Read Variable: | [STX]sRN filterDepth[ETX] |
| Read Variable Response: | [STX]sRA filterDepth 1[ETX] |
| Write Variable: | [STX]sWN filterDepth 1[ETX] |
| Write Variable Response: | [STX]sWA filterDepth[ETX] |

3.1.1.2.3 Variable: echoSelectionMode [echo selection: first echo or last echo]

The following section contains a detailed description of the variable echoSelectionMode.

Variable Overview

| Variable Name | Description | | |
|-------------------|---------------------------|-------------------|--|
| echoSelectionMode | Echo Selection Mode | | |
| Read-Access | Always | | |
| Write-Access | AuthorizedClient, Service | | |
| Enum8 | | | |
| Default Value | FIRST_ECHO | | |
| Value | Name | Description | |
| 0 | FIRST_ECHO | Select first echo | |
| 1 | LAST_ECHO | Select last echo | |

Variable Telegram Syntax

Read Variable:

sRN echoSelectionMode

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-------------------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | echoSelectionMode | String | 16 | Echo Selection Mode |

Read Variable Response:

sRA echoSelectionMode <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-------------------|--------|---------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | echoSelectionMode | String | 16 | Echo Selection Mode |
| Variable Data | data | Enum8 | 1 | |

Write Variable:

sWN echoSelectionMode <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-------------------|--------|---------------|------------------------------|
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | echoSelectionMode | String | 16 | Echo Selection Mode |
| Variable Data | data | Enum8 | 1 | |

Write Variable Response:

sWA echoSelectionMode

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-------------------|--------|---------------|----------------------------------|
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | echoSelectionMode | String | 16 | Echo Selection Mode |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|--------------------------|-----------------------------------|
| Read Variable: | [STX]sRN echoSelectionMode[ETX] |
| Read Variable Response: | [STX]sRA echoSelectionMode 0[ETX] |
| Write Variable: | [STX]sWN echoSelectionMode 0[ETX] |
| Write Variable Response: | [STX]sWA echoSelectionMode[ETX] |

3.1.1.2.4 Variable: roiStart [distance range: measuring range limit facing the device]

The following section contains a detailed description of the variable roiStart.

Variable Overview

| Variable Name | Description |
|----------------|---------------------------|
| roiStart | Start of ROI in mm |
| Read-Access | Always |
| Write-Access | AuthorizedClient, Service |
| DInt | |
| Value Range | 100..1500000 |
| Initialisation | 500 |
| Physical Unit | mm |

Variable Telegram Syntax

Read Variable:

sRN roiStart

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | roiStart | String | 8 | Start of ROI in mm |

Read Variable Response:

sRA roiStart <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------|--------|---------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | roiStart | String | 8 | Start of ROI in mm |
| Variable Data | data | DInt | 4 | |

Write Variable:

sWN roiStart <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------|--------|---------------|------------------------------|
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | roiStart | String | 8 | Start of ROI in mm |
| Variable Data | data | DInt | 4 | |

Write Variable Response:

sWA roiStart

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------|--------|---------------|----------------------------------|
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | roiStart | String | 8 | Start of ROI in mm |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|--------------------------|----------------------------|
| Read Variable: | [STX]sRN roiStart[ETX] |
| Read Variable Response: | [STX]sRA roiStart 1F4[ETX] |
| Write Variable: | [STX]sWN roiStart 1F4[ETX] |
| Write Variable Response: | [STX]sWA roiStart[ETX] |

3.1.1.2.5 Variable: roiEnd [distance range: measuring range limit facing away from the device]

The following section contains a detailed description of the variable roiEnd.

Variable Overview

| Variable Name | Description |
|----------------|---------------------------|
| roiEnd | End of ROI in mm |
| Read-Access | Always |
| Write-Access | AuthorizedClient, Service |
| DInt | |
| Value Range | 100..1500000 |
| Initialisation | 1500000 |
| Physical Unit | mm |

Variable Telegram Syntax

Read Variable:

sRN roiEnd

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | roiEnd | String | 6 | End of ROI in mm |

Read Variable Response:

sRA roiEnd <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------|--------|---------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | roiEnd | String | 6 | End of ROI in mm |
| Variable Data | data | DInt | 4 | |

Write Variable:

sWN roiEnd <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------|--------|---------------|------------------------------|
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | roiEnd | String | 6 | End of ROI in mm |

Write Variable:

sWN roiEnd <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------|------|---------------|-------------|
| Variable Data | data | DInt | 4 | |

Write Variable Response:

sWA roiEnd

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------|--------|---------------|----------------------------------|
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | roiEnd | String | 6 | End of ROI in mm |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|--------------------------|-----------------------------|
| Read Variable: | [STX]sRN roiEnd[ETX] |
| Read Variable Response: | [STX]sRA roiEnd 16E360[ETX] |
| Write Variable: | [STX]sWN roiEnd 16E360[ETX] |
| Write Variable Response: | [STX]sWA roiEnd[ETX] |

3.1.1.2.6 Variable: roiMinLevel [signal level range: lower signal level limit]

The following section contains a detailed description of the variable roiMinLevel.

Variable Overview

| Variable Name | Description |
|----------------|----------------------------|
| roiMinLevel | Min level for echos in ROI |
| Read-Access | Always |
| Write-Access | AuthorizedClient, Service |
| DInt | |
| Value Range | 0..16383 |
| Initialisation | 0 |

Variable Telegram Syntax

| Read Variable: | | | | |
|---------------------------------|-------------|--------|---------------|----------------------------------|
| sRN roiMinLevel | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | roiMinLevel | String | 11 | Min level for echos in ROI |
| Read Variable Response: | | | | |
| sRA roiMinLevel <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | roiMinLevel | String | 11 | Min level for echos in ROI |
| Variable Data | data | DInt | 4 | |
| Write Variable: | | | | |
| sWN roiMinLevel <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | roiMinLevel | String | 11 | Min level for echos in ROI |
| Variable Data | data | DInt | 4 | |
| Write Variable Response: | | | | |
| sWA roiMinLevel | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | roiMinLevel | String | 11 | Min level for echos in ROI |

Variable Telegram Examples

| Example: Default Values | |
|---|-----------------------------|
| Variable telegram examples with data set to default values. | |
| Read Variable: | [STX]sRN roiMinLevel[ETX] |
| Read Variable Response: | [STX]sRA roiMinLevel 0[ETX] |
| Write Variable: | [STX]sWN roiMinLevel 0[ETX] |
| Write Variable Response: | [STX]sWA roiMinLevel[ETX] |

3.1.1.2.7 Variable: roiMaxLevel [signal level range: upper signal level limit]

The following section contains a detailed description of the variable roiMaxLevel.

Variable Overview

| Variable Name | Description |
|----------------|----------------------------|
| roiMaxLevel | Min level for echos in ROI |
| Read-Access | Always |
| Write-Access | AuthorizedClient, Service |
| DInt | |
| Value Range | 0..16383 |
| Initialisation | 16383 |

Variable Telegram Syntax

| Read Variable: | | | | |
|--------------------------|-------------|--------|---------------|----------------------------------|
| sRN roiMaxLevel | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | roiMaxLevel | String | 11 | Min level for echos in ROI |
| Read Variable Response: | | | | |
| sRA roiMaxLevel <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | roiMaxLevel | String | 11 | Min level for echos in ROI |
| Variable Data | data | DInt | 4 | |
| Write Variable: | | | | |
| sWN roiMaxLevel <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | roiMaxLevel | String | 11 | Min level for echos in ROI |
| Variable Data | data | DInt | 4 | |
| Write Variable Response: | | | | |
| swA roiMaxLevel | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | roiMaxLevel | String | 11 | Min level for echos in ROI |

Variable Telegram Examples

| Example: Default Values |
|---|
| Variable telegram examples with data set to default values. |
| Read Variable: [STX]sRN roiMaxLevel[ETX] |
| Read Variable Response: [STX]sRA roiMaxLevel 3FFF[ETX] |
| Write Variable: [STX]sWN roiMaxLevel 3FFF[ETX] |
| Write Variable Response: [STX]sWA roiMaxLevel[ETX] |

3.1.1.2.8 Variable: noEchoOutputMode [substitute values for "no echo"]

The following section contains a detailed description of the variable noEchoOutputMode.

Variable Overview

| Variable Name | Description | |
|------------------|---|--|
| noEchoOutputMode | Defines the sensor behaviour after max bridging time exceeded | |
| Read-Access | Always | |
| Write-Access | AuthorizedClient, Service | |
| Enum8 | | |
| Default Value | REPLACEMENT | |
| Value | Name | Description |
| 0 | HOLD | Keep the last valid distance and velocity value |
| 1 | REPLACEMENT | Replace distance and velocity with the NoEchoOutput values |

Variable Telegram Syntax

| Read Variable: | | | | |
|---------------------------------|------------------|--------|---------------|---|
| sRN noEchoOutputMode | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | noEchoOutputMode | String | 16 | Defines the sensor behaviour after max bridging time exceeded |
| Read Variable Response: | | | | |
| sRA noEchoOutputMode <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | noEchoOutputMode | String | 16 | Defines the sensor behaviour after max bridging time exceeded |
| Variable Data | data | Enum8 | 1 | |
| Write Variable: | | | | |
| sWN noEchoOutputMode <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | noEchoOutputMode | String | 16 | Defines the sensor behaviour after max bridging time exceeded |
| Variable Data | data | Enum8 | 1 | |
| Write Variable Response: | | | | |
| sWA noEchoOutputMode | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | noEchoOutputMode | String | 16 | Defines the sensor behaviour after max bridging time exceeded |

Variable Telegram Examples

| | | | | |
|---|----------------------------------|--|--|--|
| Example: Default Values | | | | |
| Variable telegram examples with data set to default values. | | | | |
| Read Variable: | [STX]sRN noEchoOutputMode [ETX] | | | |
| Read Variable Response: | [STX]sRA noEchoOutputMode 1[ETX] | | | |
| Write Variable: | [STX]sWN noEchoOutputMode 1[ETX] | | | |
| Write Variable Response: | [STX]sWA noEchoOutputMode [ETX] | | | |

3.1.1.2.9 Variable: noEchoOutputDistance [user-defined substitute values: distance]

The following section contains a detailed description of the variable noEchoOutputDistance.

Variable Overview

| Variable Name | Description |
|----------------------|--|
| noEchoOutputDistance | Distance in mm that shall be set it no echo is found |
| Read-Access | Always |
| Write-Access | AuthorizedClient, Service |
| DInt | |
| Value Range | -6096000..6096000 |
| Initialisation | 6096000 |
| Physical Unit | mm |

Variable Telegram Syntax

Read Variable:

```
sRN noEchoOutputDistance
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------------------|--------|---------------|--|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | noEchoOutputDistance | String | 20 | Distance in mm that shall be set it no echo is found |

Read Variable Response:

```
sRA noEchoOutputDistance <data>
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------------------|--------|---------------|--|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | noEchoOutputDistance | String | 20 | Distance in mm that shall be set it no echo is found |
| Variable Data | data | DInt | 4 | |

Write Variable:

```
sWN noEchoOutputDistance <data>
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------------------|--------|---------------|--|
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | noEchoOutputDistance | String | 20 | Distance in mm that shall be set it no echo is found |
| Variable Data | data | DInt | 4 | |

Write Variable Response:

```
sWA noEchoOutputDistance
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------------------|--------|---------------|--|
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | noEchoOutputDistance | String | 20 | Distance in mm that shall be set it no echo is found |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|--------------------------|---|
| Read Variable: | [STX]sRN noEchoOutputDistance[ETX] |
| Read Variable Response: | [STX]sRA noEchoOutputDistance 5D0480[ETX] |
| Write Variable: | [STX]sWN noEchoOutputDistance 5D0480[ETX] |
| Write Variable Response: | [STX]sWA noEchoOutputDistance[ETX] |

3.1.1.2.10 Variable: noEchoOutputVelocity [user-defined substitute values: speed]

The following section contains a detailed description of the variable noEchoOutputVelocity.

Variable Overview

| Variable Name | Description |
|----------------------|--|
| noEchoOutputVelocity | Velocity in mm/s that shall be set if no echo is found |
| Read-Access | Always |
| Write-Access | AuthorizedClient, Service |
| DInt | |
| Value Range | -20000..20000 |
| Initialisation | 0 |
| Physical Unit | mm/s |

Variable Telegram Syntax

Read Variable:

```
sRN noEchoOutputVelocity
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------------------|--------|---------------|--|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | noEchoOutputVelocity | String | 20 | Velocity in mm/s that shall be set if no echo is found |

Read Variable Response:

```
sRA noEchoOutputVelocity <data>
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------------------|--------|---------------|--|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | noEchoOutputVelocity | String | 20 | Velocity in mm/s that shall be set if no echo is found |
| Variable Data | data | DInt | 4 | |

Write Variable:

```
sWN noEchoOutputVelocity <data>
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------------------|--------|---------------|--|
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | noEchoOutputVelocity | String | 20 | Velocity in mm/s that shall be set if no echo is found |
| Variable Data | data | DInt | 4 | |

Write Variable Response:

```
sWA noEchoOutputVelocity
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------------------|--------|---------------|--|
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | noEchoOutputVelocity | String | 20 | Velocity in mm/s that shall be set if no echo is found |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|--------------------------|--------------------------------------|
| Read Variable: | [STX]sRN noEchoOutputVelocity[ETX] |
| Read Variable Response: | [STX]sRA noEchoOutputVelocity 0[ETX] |
| Write Variable: | [STX]sWN noEchoOutputVelocity 0[ETX] |
| Write Variable Response: | [STX]sWA noEchoOutputVelocity[ETX] |

3.1.1.2.11 Variable: errorOutputDistance [behaviour on error: user-defined substitute values: distance]

The following section contains a detailed description of the variable errorOutputDistance.

Variable Overview

| Variable Name | Description |
|---------------------|--|
| errorOutputDistance | Distance in mm that shall be set if error is present |
| Read-Access | Always |
| Write-Access | AuthorizedClient, Service |
| DInt | |
| Value Range | -6096000..6096000 |
| Initialisation | 0 |
| Physical Unit | mm |

Variable Telegram Syntax

Read Variable:

```
sRN errorOutputDistance
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|---------------------|--------|---------------|--|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | errorOutputDistance | String | 19 | Distance in mm that shall be set if error is present |

Read Variable Response:

```
sRA errorOutputDistance <data>
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|---------------------|--------|---------------|--|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | errorOutputDistance | String | 19 | Distance in mm that shall be set if error is present |
| Variable Data | data | DInt | 4 | |

Write Variable:

```
sWN errorOutputDistance <data>
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|---------------------|--------|---------------|--|
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | errorOutputDistance | String | 19 | Distance in mm that shall be set if error is present |

Write Variable:

```
sWA errorOutputDistance <data>
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------|------|---------------|-------------|
| Variable Data | data | DInt | 4 | |

Write Variable Response:

```
sWA errorOutputDistance
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|---------------------|--------|---------------|--|
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | errorOutputDistance | String | 19 | Distance in mm that shall be set if error is present |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|--------------------------|-------------------------------------|
| Read Variable: | [STX]sRN errorOutputDistance[ETX] |
| Read Variable Response: | [STX]sRA errorOutputDistance 0[ETX] |
| Write Variable: | [STX]sWN errorOutputDistance 0[ETX] |
| Write Variable Response: | [STX]sWA errorOutputDistance[ETX] |

3.1.1.2.12 Variable: errorOutputVelocity [behaviour on error: user-defined substitute values: speed]

The following section contains a detailed description of the variable errorOutputVelocity.

Variable Overview

| Variable Name | Description |
|---------------------|--|
| errorOutputVelocity | Velocity in mm/s that shall be set if error is present |
| Read-Access | Always |
| Write-Access | AuthorizedClient, Service |
| DInt | |
| Value Range | -20000..20000 |
| Initialisation | 0 |
| Physical Unit | mm/s |

Variable Telegram Syntax

Read Variable:

```
sRN errorOutputVelocity
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|---------------------|--------|---------------|--|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | errorOutputVelocity | String | 19 | Velocity in mm/s that shall be set if error is present |

Read Variable Response:

```
sRA errorOutputVelocity <data>
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|---------------------|--------|---------------|--|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | errorOutputVelocity | String | 19 | Velocity in mm/s that shall be set if error is present |
| Variable Data | data | DInt | 4 | |

Write Variable:

```
sWN errorOutputVelocity <data>
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|---------------------|--------|---------------|--|
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | errorOutputVelocity | String | 19 | Velocity in mm/s that shall be set if error is present |
| Variable Data | data | DInt | 4 | |

Write Variable Response:

```
sWA errorOutputVelocity
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|---------------------|--------|---------------|--|
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | errorOutputVelocity | String | 19 | Velocity in mm/s that shall be set if error is present |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|--------------------------|-------------------------------------|
| Read Variable: | [STX]sRN errorOutputVelocity[ETX] |
| Read Variable Response: | [STX]sRA errorOutputVelocity 0[ETX] |
| Write Variable: | [STX]sWN errorOutputVelocity 0[ETX] |
| Write Variable Response: | [STX]sWA errorOutputVelocity[ETX] |

3.1.2 Interface

3.1.2.1 Variable: preset [switching input: preset value]

The following section contains a detailed description of the variable preset.

Variable Overview

| Variable Name | Description |
|----------------|---------------------------|
| preset | Preset in mm |
| Read-Access | Always |
| Write-Access | AuthorizedClient, Service |
| DInt | |
| Value Range | -1500000..1500000 |
| Initialisation | 0 |

Variable Telegram Syntax

| Read Variable: | | | | |
|--------------------------|----------|--------|---------------|----------------------------------|
| sRN preset | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | preset | String | 6 | Preset in mm |
| Read Variable Response: | | | | |
| sRA preset <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | preset | String | 6 | Preset in mm |
| Variable Data | data | DInt | 4 | |
| Write Variable: | | | | |
| sWN preset <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | preset | String | 6 | Preset in mm |
| Variable Data | data | DInt | 4 | |
| Write Variable Response: | | | | |
| sWA preset | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | preset | String | 6 | Preset in mm |

Variable Telegram Examples

| Example: Default Values |
|---|
| Variable telegram examples with data set to default values. |
| Read Variable: [STX]sRN preset[ETX] |
| Read Variable Response: [STX]sRA preset 0[ETX] |
| Write Variable: [STX]sWN preset 0[ETX] |
| Write Variable Response: [STX]sWA preset[ETX] |

3.1.2.2 Variable: configIo1 [selection: In/Q1 as digital input or output]

The following section contains a detailed description of the variable configIo1.

Variable Overview

| Variable Name | Description | | | | |
|-------------------|---|---------|--|--|--|
| configIo1 | Configuration of IO1 | | | | |
| Read-Access | AuthorizedClient, Service | | | | |
| Write-Access | AuthorizedClient, Service | | | | |
| Struct | | | | | |
| Dir | | | | | |
| Enum8 | | | | | |
| Default Value | OUTPUT | | | | |
| Value | Name | | | | |
| | 0 | INPUT | | | |
| 1 | OUTPUT | | | | |
| | | | | | |
| Type | | | | | |
| Enum8 | | | | | |
| Default Value | DIGITAL | | | | |
| Value | Name | | | | |
| | 0 | DIGITAL | | | |
| Cfg | | | | | |
| UserType | | | | | |
| ioConfiguration_t | See the chapter "User Types" for details. | | | | |

Variable Telegram Syntax

| Read Variable: | | | | |
|----------------------------------|-----------|-------------------|---------------|---------------------------------|
| sRN configIo1 | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | configIo1 | String | 9 | Configuration of IO1 |
| Read Variable Response: | | | | |
| sRA configIo1 <Dir> <Type> <Cfg> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | configIo1 | String | 9 | Configuration of IO1 |
| Variable Data 1 | Dir | Enum8 | 1 | |
| Variable Data 2 | Type | Enum8 | 1 | |
| Variable Data 3 | Cfg | ioConfiguration_t | 0 | |
| Write Variable: | | | | |
| sWN configIo1 <Dir> <Type> <Cfg> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | configIo1 | String | 9 | Configuration of IO1 |
| Variable Data 1 | Dir | Enum8 | 1 | |
| Variable Data 2 | Type | Enum8 | 1 | |
| Variable Data 3 | Cfg | ioConfiguration_t | 0 | |

| Write Variable Response: | | | | |
|--------------------------|-----------|--------|---------------|----------------------------------|
| sWA configIo1 | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | configIo1 | String | 9 | Configuration of IO1 |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|---------------------------------|--|
| Read Variable: | [STX]sRN configIo1[ETX] |
| Read Variable Response: | [STX]sRA configIo1 1 0 0 0 2 3 2710 4E20 64 1388 32 1 1 1 1 1 1 0 0 0 0 0 0 1 [ETX] |
| Write Variable: | [STX]sWN configIo1 1 0 0 0 2 3 2710 4E20 64 1388 32 1 1 1 1 1 1 0 0 0 0 0 0 1 [ETX] |
| Write Variable Response: | [STX]sWA configIo1[ETX] |

3.1.2.3 Variable: configIo2 [selection: QA/Q2 as analog input or digital output]

The following section contains a detailed description of the variable configIo2.

Variable Overview

| Variable Name | Description | | |
|-------------------|---|---------|-------------|
| configIo2 | Configuration of IO2 | | |
| Read-Access | AuthorizedClient, Service | | |
| Write-Access | AuthorizedClient, Service | | |
| Struct | | | |
| Dir | | | |
| Enum8 | | | |
| Default Value | OUTPUT | | |
| | Value | Name | Description |
| | 1 | OUTPUT | |
| Type | | | |
| Enum8 | | | |
| Default Value | DIGITAL | | |
| | Value | Name | Description |
| | 0 | DIGITAL | |
| | 1 | ANALOG | |
| Cfg | | | |
| UserType | | | |
| ioConfiguration_t | See the chapter "User Types" for details. | | |

Variable Telegram Syntax

Read Variable:

sRN configIo2

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | configIo2 | String | 9 | Configuration of IO2 |

Read Variable Response:

sRA configIo2 <Dir> <Type> <Cfg>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|-----------------|-----------|-------------------|---------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | configIo2 | String | 9 | Configuration of IO2 |
| Variable Data 1 | Dir | Enum8 | 1 | |
| Variable Data 2 | Type | Enum8 | 1 | |
| Variable Data 3 | Cfg | ioConfiguration_t | 0 | |

| Write Variable: | | | | |
|----------------------------------|-----------------|-----------------------|----------------------|------------------------------|
| sWN configIo2 <Dir> <Type> <Cfg> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | configIo2 | String | 9 | Configuration of IO2 |
| Variable Data 1 | Dir | Enum8 | 1 | |
| Variable Data 2 | Type | Enum8 | 1 | |
| Variable Data 3 | Cfg | ioConfigurati on_t | 0 | |

| Write Variable Response: | | | | |
|---------------------------------|-----------------|-------------|----------------------|----------------------------------|
| sWA configIo2 | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | configIo2 | String | 9 | Configuration of IO2 |

Variable Telegram Examples

| Example: Default Values | |
|---|--|
| Variable telegram examples with data set to default values. | |
| Read Variable: | [STX]sRN configIo2[ETX] |
| Read Variable Response: | [STX]sRA configIo2 1 0 0 0 2 3 2710 4E20 64 1388 32 1 1 1 1 1 0 0 0 0 0 0 1[ETX] |
| Write Variable: | [STX]sWN configIo2 1 0 0 0 2 3 2710 4E20 64 1388 32 1 1 1 1 1 0 0 0 0 0 0 1[ETX] |
| Write Variable Response: | [STX]sWA configIo2[ETX] |

3.1.2.4 Variable: configIo3 [selection: Q3 as digital output]

The following section contains a detailed description of the variable configIo3.

Variable Overview

| Variable Name | Description |
|----------------------|---------------------------|
| configIo3 | Configuration of IO3 |
| Read-Access | AuthorizedClient, Service |
| Write-Access | AuthorizedClient, Service |

| Struct | |
|---------------|--------|
| Dir | |
| Enum8 | |
| Default Value | OUTPUT |
| Value | Name |
| 1 | OUTPUT |

| Struct | |
|-------------------|---|
| Type | |
| Enum8 | |
| Default Value | DIGITAL |
| Value | Name |
| 0 | DIGITAL |
| Cfg | |
| UserType | |
| ioConfiguration_t | See the chapter "User Types" for details. |

Variable Telegram Syntax

Read Variable:

```
sRN configIo3
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | configIo3 | String | 9 | Configuration of IO3 |

Read Variable Response:

```
sRA configIo3 <Dir> <Type> <Cfg>
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|-----------------|-----------|-----------------------|---------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | configIo3 | String | 9 | Configuration of IO3 |
| Variable Data 1 | Dir | Enum8 | 1 | |
| Variable Data 2 | Type | Enum8 | 1 | |
| Variable Data 3 | Cfg | ioConfigurati on_t | 0 | |

Write Variable:

```
sWN configIo3 <Dir> <Type> <Cfg>
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|-----------------|-----------|-----------------------|---------------|------------------------------|
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | configIo3 | String | 9 | Configuration of IO3 |
| Variable Data 1 | Dir | Enum8 | 1 | |
| Variable Data 2 | Type | Enum8 | 1 | |
| Variable Data 3 | Cfg | ioConfigurati on_t | 0 | |

Write Variable Response:

```
sWA configIo3
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------|--------|---------------|----------------------------------|
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | configIo3 | String | 9 | Configuration of IO3 |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|--------------------------|---|
| Read Variable: | [STX]sRN configIo3[ETX] |
| Read Variable Response: | [STX]sRA configIo3 1 0 0 0 2 3 2710 4E20 64 1388 32 1 1 1 1 1 0 0 0 0 0 0 1 [ETX] |
| Write Variable: | [STX]sWN configIo3 1 0 0 0 2 3 2710 4E20 64 1388 32 1 1 1 1 1 0 0 0 0 0 0 1 [ETX] |
| Write Variable Response: | [STX]sWA configIo3[ETX] |

3.1.2.5 Variable: configIo4 [selection: Q4 as digital output]

The following section contains a detailed description of the variable configIo4.

Variable Overview

| Variable Name | Description |
|---------------|---------------------------|
| configIo4 | Configuration of IO4 |
| Read-Access | AuthorizedClient, Service |
| Write-Access | AuthorizedClient, Service |

| Struct | | | | | | |
|-------------------|---|---------|-------------|--|--|--|
| Dir | | | | | | |
| Enum8 | | | | | | |
| Default Value | OUTPUT | | | | | |
| | Value | Name | Description | | | |
| | 1 | OUTPUT | | | | |
| Type | | | | | | |
| Enum8 | | | | | | |
| Default Value | DIGITAL | | | | | |
| | Value | Name | Description | | | |
| | 0 | DIGITAL | | | | |
| Cfg | | | | | | |
| UserType | | | | | | |
| ioConfiguration_t | See the chapter "User Types" for details. | | | | | |

Variable Telegram Syntax

Read Variable:

sRN configIo4

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------|----------------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | configIo4 | String | 9 | Configuration of IO4 |

Read Variable Response:

sRA configIo4 <Dir> <Type> <Cfg>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------------|----------------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | configIo4 | String | 9 | Configuration of IO4 |
| Variable Data 1 | Dir | Enum8 | 1 | |
| Variable Data 2 | Type | Enum8 | 1 | |
| Variable Data 3 | Cfg | ioConfiguration_t | 0 | |

Write Variable:

sWN configIo4 <Dir> <Type> <Cfg>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------------|----------------------|------------------------------|
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | configIo4 | String | 9 | Configuration of IO4 |
| Variable Data 1 | Dir | Enum8 | 1 | |
| Variable Data 2 | Type | Enum8 | 1 | |
| Variable Data 3 | Cfg | ioConfiguration_t | 0 | |

Write Variable Response:

sWA configIo4

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------|----------------------|----------------------------------|
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | configIo4 | String | 9 | Configuration of IO4 |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|---------------------------------|---|
| Read Variable: | [STX] sRN configIo4[ETX] |
| Read Variable Response: | [STX] sRA configIo4 1 0 0 0 2 3 2710 4E20 64 1388 32 1 1 1 1 1 0 0 0 0 0 0 1[ETX] |
| Write Variable: | [STX] sWN configIo4 1 0 0 0 2 3 2710 4E20 64 1388 32 1 1 1 1 1 0 0 0 0 0 0 1[ETX] |
| Write Variable Response: | [STX] sWA configIo4[ETX] |

3.1.2.6 Variable: configIo5 [selection: In2 as digital input]

The following section contains a detailed description of the variable configIo5.

Variable Overview

| Variable Name | Description | | |
|-------------------|---|---------|-------------|
| configIo5 | Configuration of IO5 | | |
| Read-Access | AuthorizedClient, Service | | |
| Write-Access | AuthorizedClient, Service | | |
| Struct | | | |
| Dir | | | |
| Enum8 | | | |
| Default Value | INPUT | | |
| | Value | Name | Description |
| | 0 | INPUT | |
| Type | | | |
| Enum8 | | | |
| Default Value | DIGITAL | | |
| | Value | Name | Description |
| | 0 | DIGITAL | |
| Cfg | | | |
| UserType | | | |
| ioConfiguration_t | See the chapter "User Types" for details. | | |

Variable Telegram Syntax

Read Variable:

```
sRN configIo5
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | configIo5 | String | 9 | Configuration of IO5 |

Read Variable Response:

```
sRA configIo5 <Dir> <Type> <Cfg>
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|-----------------|-----------|-------------------|---------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | configIo5 | String | 9 | Configuration of IO5 |
| Variable Data 1 | Dir | Enum8 | 1 | |
| Variable Data 2 | Type | Enum8 | 1 | |
| Variable Data 3 | Cfg | ioConfiguration_t | 0 | |

Write Variable:

```
sWN configIo5 <Dir> <Type> <Cfg>
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------|--------|---------------|------------------------------|
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |

Write Variable:

```
sWN configIo5 <Dir> <Type> <Cfg>
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|-----------------|-----------|-------------------|---------------|----------------------|
| Command | configIo5 | String | 9 | Configuration of IO5 |
| Variable Data 1 | Dir | Enum8 | 1 | |
| Variable Data 2 | Type | Enum8 | 1 | |
| Variable Data 3 | Cfg | ioConfiguration_t | 0 | |

Write Variable Response:

sWA configIo5

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------|--------|---------------|----------------------------------|
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | configIo5 | String | 9 | Configuration of I05 |

Variable Telegram Examples**Example: Default Values**

Variable telegram examples with data set to default values.

| | |
|---------------------------------|---|
| Read Variable: | [STX] sRN configIo5[ETX] |
| Read Variable Response: | [STX] sRA configIo5 0 0 0 0 2 3 2710 4E20 64 1388 32 1 1 1 1 1 1 0 0 0 0 0 0 1[ETX] |
| Write Variable: | [STX] sWN configIo5 0 0 0 0 2 3 2710 4E20 64 1388 32 1 1 1 1 1 1 0 0 0 0 0 0 1[ETX] |
| Write Variable Response: | [STX] sWA configIo5[ETX] |

3.1.3 Device

3.1.3.1 Laser

3.1.3.1.1 Method: enableMeasurementLaser [switching the measurement laser on/off: on]

The following section contains a detailed description of the method enableMeasurementLaser.

Method Overview

| Method Name | Description | |
|------------------------|--|--|
| enableMeasurementLaser | Enable Measurement Laser | |
| Invocation Access | AuthorizedClient, Service | |
| Return Values | | |
| success | Bool Value Range False, True Initialisation False | |

Method Telegram Syntax**Method Invocation:**

sMN enableMeasurementLaser

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|------------------------|--------|---------------|--------------------------------|
| Command Type | sMN | String | 3 | Request (SOPAS Method by Name) |
| Command | enableMeasurementLaser | String | 22 | Enable Measurement Laser |

Method Return Value:

sAN enableMeasurementLaser <success>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------|------------------------|--------|---------------|------------------------------|
| Command Type | sAN | String | 3 | Result (SOPAS Method Result) |
| Command | enableMeasurementLaser | String | 22 | Enable Measurement Laser |
| Return Value 1 | success | Bool | 1 | |

Method Telegram Examples**Example: Default Values**

Method telegram examples with parameter data and return value data set to default values.

| | |
|-----------------------------|---|
| Method Invocation: | [STX] sMN enableMeasurementLaser[ETX] |
| Method Return Value: | [STX] sAN enableMeasurementLaser 0[ETX] |

3.1.3.1.2 Method: disableMeasurementLaser [Switching the measurement laser on/off: off]

The following section contains a detailed description of the method disableMeasurementLaser.

Method Overview

| Method Name | Description |
|-------------------------|---------------------------|
| disableMeasurementLaser | Disable Measurement Laser |
| Invocation Access | AuthorizedClient, Service |
| Return Values | |
| success | |
| Bool | |
| Value Range | False, True |
| Initialisation | False |

Method Telegram Syntax

| Method Invocation: | | | | |
|-----------------------------|---|--------|---------------|--------------------------------|
| sMN disableMeasurementLaser | | | | |
| Method Return Value: | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sMN | String | 3 | Request (SOPAS Method by Name) |
| Command | disableMeasurementLaser | String | 23 | Disable Measurement Laser |
| Method Invocation: | [STX]sMN disableMeasurementLaser[ETX] | | | |
| Method Return Value: | [STX]sAN disableMeasurementLaser 0[ETX] | | | |

Method Telegram Examples

| Example: Default Values | |
|---|---|
| Method telegram examples with parameter data and return value data set to default values. | |
| Method Invocation: | [STX]sMN disableMeasurementLaser[ETX] |
| Method Return Value: | [STX]sAN disableMeasurementLaser 0[ETX] |

3.1.3.1.3 Method: enablePilotLaser [switching the alignmentt laser on/off: on]

The following section contains a detailed description of the method enablePilotLaser.

Method Overview

| Method Name | Description |
|-------------------|---------------------------|
| enablePilotLaser | Enable Pilot Laser |
| Invocation Access | AuthorizedClient, Service |
| Return Values | |
| success | |
| Bool | |
| Value Range | False, True |
| Initialisation | False |

Method Telegram Syntax

| Method Invocation: | | | | |
|----------------------|------------------|--------|---------------|--------------------------------|
| sMN enablePilotLaser | | | | |
| Method Return Value: | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sMN | String | 3 | Request (SOPAS Method by Name) |
| Command | enablePilotLaser | String | 16 | Enable Pilot Laser |

| Method Return Value: | | | | |
|--------------------------------|------------------|-------------|----------------------|------------------------------|
| sAN enablePilotLaser <success> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sAN | String | 3 | Result (SOPAS Method Result) |
| Command | enablePilotLaser | String | 16 | Enable Pilot Laser |
| Return Value 1 | success | Bool | 1 | |

Method Telegram Examples

Example: Default Values

Method telegram examples with parameter data and return value data set to default values.

| | |
|-----------------------------|----------------------------------|
| Method Invocation: | [STX]sMN enablePilotLaser[ETX] |
| Method Return Value: | [STX]sAN enablePilotLaser 0[ETX] |

3.1.3.1.4 Method: disablePilotLaser [switching the alignment laser on/off: off]

The following section contains a detailed description of the method disablePilotLaser.

Method Overview

| Method Name | Description |
|----------------------|---------------------------|
| disablePilotLaser | Disable Pilot Laser |
| Invocation Access | AuthorizedClient, Service |
| Return Values | |
| success | |
| Bool | |
| Value Range | False, True |
| Initialisation | False |

Method Telegram Syntax

Method Invocation:

sMN disablePilotLaser

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-------------------|-------------|----------------------|--------------------------------|
| Command Type | sMN | String | 3 | Request (SOPAS Method by Name) |
| Command | disablePilotLaser | String | 17 | Disable Pilot Laser |

Method Return Value:

sAN disablePilotLaser <success>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-------------------|-------------|----------------------|------------------------------|
| Command Type | sAN | String | 3 | Result (SOPAS Method Result) |
| Command | disablePilotLaser | String | 17 | Disable Pilot Laser |
| Return Value 1 | success | Bool | 1 | |

Method Telegram Examples

Example: Default Values

Method telegram examples with parameter data and return value data set to default values.

| | |
|-----------------------------|-----------------------------------|
| Method Invocation: | [STX]sMN disablePilotLaser[ETX] |
| Method Return Value: | [STX]sAN disablePilotLaser 0[ETX] |

3.1.3.2 Heater

3.1.3.2.1 Variable: heaterSwitchingThreshold [switch-on temperature]

The following section contains a detailed description of the variable heaterSwitchingThreshold.

Variable Overview

| Variable Name | Description |
|--------------------------|--|
| heaterSwitchingThreshold | If temperature falls below this level the heater will be switched on |
| Read-Access | Always |
| Write-Access | AuthorizedClient, Service |
| SInt | |
| Value Range | -20..20 |
| Initialisation | -10 |
| Physical Unit | °C |

Variable Telegram Syntax

| Read Variable: | | | | |
|-------------------------------------|--------------------------|--------|---------------|--|
| sRN heaterSwitchingThreshold | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | heaterSwitchingThreshold | String | 24 | If temperature falls below this level the heater will be switched on |
| Read Variable Response: | | | | |
| sRA heaterSwitchingThreshold <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | heaterSwitchingThreshold | String | 24 | If temperature falls below this level the heater will be switched on |
| Variable Data | data | SInt | 1 | |
| Write Variable: | | | | |
| sWN heaterSwitchingThreshold <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | heaterSwitchingThreshold | String | 24 | If temperature falls below this level the heater will be switched on |
| Variable Data | data | SInt | 1 | |
| Write Variable Response: | | | | |
| sWA heaterSwitchingThreshold | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | heaterSwitchingThreshold | String | 24 | If temperature falls below this level the heater will be switched on |

Variable Telegram Examples

| Example: Default Values | |
|---|---|
| Variable telegram examples with data set to default values. | |
| Read Variable: | [STX]sRN heaterSwitchingThreshold[ETX] |
| Read Variable Response: | [STX]sRA heaterSwitchingThreshold F6[ETX] |
| Write Variable: | [STX]sWN heaterSwitchingThreshold F6[ETX] |
| Write Variable Response: | [STX]sWA heaterSwitchingThreshold[ETX] |

3.1.3.2.2 Method: switchHeaterOn [heating on]

The following section contains a detailed description of the method switchHeaterOn.

Method Overview

| Method Name | Description |
|-------------------|---------------------------|
| switchHeaterOn | Switch Heater on |
| Invocation Access | AuthorizedClient, Service |

Method Telegram Syntax

| Method Invocation: | | | | |
|----------------------|----------------|--------|---------------|--------------------------------|
| sMN switchHeaterOn | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sMN | String | 3 | Request (SOPAS Method by Name) |
| Command | switchHeaterOn | String | 14 | Switch Heater on |
| Method Return Value: | | | | |
| sAN switchHeaterOn | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sAN | String | 3 | Result (SOPAS Method Result) |
| Command | switchHeaterOn | String | 14 | Switch Heater on |

Method Telegram Examples

| Example: Default Values | |
|---|-------------------------------|
| Method telegram examples with parameter data and return value data set to default values. | |
| Method Invocation: | [STX] sMN switchHeaterOn[ETX] |
| Method Return Value: | [STX] sAN switchHeaterOn[ETX] |

3.1.3.2.3 Method: switchHeaterOff [heating off]

The following section contains a detailed description of the method switchHeaterOff.

Method Overview

| Method Name | Description |
|-------------------|---------------------------|
| switchHeaterOff | Switch Heater off |
| Invocation Access | AuthorizedClient, Service |

Method Telegram Syntax

| Method Invocation: | | | | |
|----------------------|-----------------|--------|---------------|--------------------------------|
| sMN switchHeaterOff | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sMN | String | 3 | Request (SOPAS Method by Name) |
| Command | switchHeaterOff | String | 15 | Switch Heater off |
| Method Return Value: | | | | |
| sAN switchHeaterOff | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sAN | String | 3 | Result (SOPAS Method Result) |
| Command | switchHeaterOff | String | 15 | Switch Heater off |

Method Telegram Examples

| Example: Default Values | |
|---|--------------------------------|
| Method telegram examples with parameter data and return value data set to default values. | |
| Method Invocation: | [STX] sMN switchHeaterOff[ETX] |
| Method Return Value: | [STX] sAN switchHeaterOff[ETX] |

3.1.3.2.4 Method: switchHeaterAuto [auto: heating is activated if the measured temperature is below the defined switch-on temperature]

The following section contains a detailed description of the method switchHeaterAuto.

Method Overview

| Method Name | Description |
|------------------|-------------------------------|
| switchHeaterAuto | Switch Heater to auto control |

| | |
|-------------------|---------------------------|
| Invocation Access | AuthorizedClient, Service |
|-------------------|---------------------------|

Method Telegram Syntax

| Method Invocation: |
|----------------------|
| sMN switchHeaterAuto |

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|------------------|--------|---------------|--------------------------------|
| Command Type | sMN | String | 3 | Request (SOPAS Method by Name) |
| Command | switchHeaterAuto | String | 16 | Switch Heater to auto control |

| Method Return Value: |
|----------------------|
| sAN switchHeaterAuto |

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|------------------|--------|---------------|-------------------------------|
| Command Type | sAN | String | 3 | Result (SOPAS Method Result) |
| Command | switchHeaterAuto | String | 16 | Switch Heater to auto control |

Method Telegram Examples

| Example: Default Values | |
|---|--------------------------------|
| Method telegram examples with parameter data and return value data set to default values. | |
| Method Invocation: | [STX]sMN switchHeaterAuto[ETX] |
| Method Return Value: | [STX]sAN switchHeaterAuto[ETX] |

3.1.3.3 Display

3.1.3.3.1 Variable: displayContrast [display contrast]

The following section contains a detailed description of the variable displayContrast.

Variable Overview

| Variable Name | Description |
|-----------------|------------------|
| displayContrast | display contrast |

| | |
|--------------|---------------------------|
| Read-Access | Always |
| Write-Access | AuthorizedClient, Service |

| USInt |
|----------------|
| Value Range |
| Initialisation |

Variable Telegram Syntax

| Read Variable: | |
|---------------------|------------------|
| sRN displayContrast | |
| Telegram Part | Telegram |
| Command Type | sRN |
| Command | displayContrast |
| Type | Length [Byte] |
| String | 3 |
| String | 15 |
| | display contrast |

| Read Variable Response: | |
|----------------------------|------------------|
| sRA displayContrast <data> | |
| Telegram Part | Telegram |
| Command Type | sRA |
| Command | displayContrast |
| Type | Length [Byte] |
| String | 3 |
| String | 15 |
| USInt | 1 |
| | display contrast |
| | variable data |

| Write Variable: | | | | |
|----------------------------|-----------------|-------------|----------------------|------------------------------|
| sWN displayContrast <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | displayContrast | String | 15 | display contrast |
| Variable Data | data | USInt | 1 | |

| Write Variable Response: | | | | |
|---------------------------------|-----------------|-------------|----------------------|----------------------------------|
| sWA displayContrast | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | displayContrast | String | 15 | display contrast |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|---------------------------------|----------------------------------|
| Read Variable: | [STX]sRN displayContrast[ETX] |
| Read Variable Response: | [STX]sRA displayContrast 32[ETX] |
| Write Variable: | [STX]sWN displayContrast 32[ETX] |
| Write Variable Response: | [STX]sWA displayContrast[ETX] |

3.1.3.3.2 Variable: displayBrightness [display brightness]

The following section contains a detailed description of the variable displayBrightness.

Variable Overview

| Variable Name | Description |
|----------------------|---------------------------|
| displayBrightness | display brightness |
| Read-Access | Always |
| Write-Access | AuthorizedClient, Service |
| USInt | |
| Value Range | 0..100 |
| Initialisation | 50 |

Variable Telegram Syntax

Read Variable:

sRN displayBrightness

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-------------------|-------------|----------------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | displayBrightness | String | 17 | display brightness |

Read Variable Response:

sRA displayBrightness <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-------------------|-------------|----------------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | displayBrightness | String | 17 | display brightness |
| Variable Data | data | USInt | 1 | |

Write Variable:

sWN displayBrightness <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-------------------|-------------|----------------------|------------------------------|
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | displayBrightness | String | 17 | display brightness |
| Variable Data | data | USInt | 1 | |

Write Variable Response:

sWA displayBrightness

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-------------------|--------|---------------|----------------------------------|
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | displayBrightness | String | 17 | display brightness |

Variable Telegram Examples**Example: Default Values**

Variable telegram examples with data set to default values.

| | |
|---------------------------------|------------------------------------|
| Read Variable: | [STX]sRN displayBrightness[ETX] |
| Read Variable Response: | [STX]sRA displayBrightness 32[ETX] |
| Write Variable: | [STX]sWN displayBrightness 32[ETX] |
| Write Variable Response: | [STX]sWA displayBrightness[ETX] |

3.1.3.3.3 Variable: displayRotation [display orientation: 0° or 180°]

The following section contains a detailed description of the variable displayRotation.

Variable Overview

| Variable Name | Description | | |
|-----------------|-------------------------------------|-------------|--|
| displayRotation | Rotation can be enabled or disabled | | |
| Read-Access | Always | | |
| Write-Access | AuthorizedClient, Service | | |
| Enum8 | | | |
| Default Value | DISABLED | | |
| Value | Name | Description | |
| 0 | DISABLED | | |
| 1 | ENABLED | | |

Variable Telegram Syntax**Read Variable:**

sRN displayRotation

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------------|--------|---------------|-------------------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | displayRotation | String | 15 | Rotation can be enabled or disabled |

Read Variable Response:

sRA displayRotation <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------------|--------|---------------|-------------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | displayRotation | String | 15 | Rotation can be enabled or disabled |
| Variable Data | data | Enum8 | 1 | |

Write Variable:

sWN displayRotation <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------------|--------|---------------|-------------------------------------|
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | displayRotation | String | 15 | Rotation can be enabled or disabled |
| Variable Data | data | Enum8 | 1 | |

Write Variable Response:

sWA displayRotation

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------------|--------|---------------|-------------------------------------|
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | displayRotation | String | 15 | Rotation can be enabled or disabled |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|---------------------------------|---------------------------------|
| Read Variable: | [STX]sRN displayRotation[ETX] |
| Read Variable Response: | [STX]sRA displayRotation 0[ETX] |
| Write Variable: | [STX]sWN displayRotation 0[ETX] |
| Write Variable Response: | [STX]sWA displayRotation[ETX] |

3.1.3.3.4 Variable: displayLanguage [language: English or German]

The following section contains a detailed description of the variable displayLanguage.

Variable Overview

| Variable Name | Description | |
|-----------------|--|-------------|
| displayLanguage | Display Language can be either german or english | |
| Read-Access | Always | |
| Write-Access | AuthorizedClient, Service | |
| Enum8 | | |
| Default Value | ENGLISH | |
| Value | Name | Description |
| 0 | GERMAN | |
| 1 | ENGLISH | |

Variable Telegram Syntax

Read Variable:

sRN displayLanguage

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------------|--------|---------------|--|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | displayLanguage | String | 15 | Display Language can be either german or english |

Read Variable Response:

sRA displayLanguage <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------------|--------|---------------|--|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | displayLanguage | String | 15 | Display Language can be either german or english |
| Variable Data | data | Enum8 | 1 | |

Write Variable:

sWN displayLanguage <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------------|--------|---------------|--|
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | displayLanguage | String | 15 | Display Language can be either german or english |
| Variable Data | data | Enum8 | 1 | |

Write Variable Response:

sWA displayLanguage

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------------|--------|---------------|--|
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | displayLanguage | String | 15 | Display Language can be either german or english |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|---------------------------------|---------------------------------|
| Read Variable: | [STX]sRN displayLanguage[ETX] |
| Read Variable Response: | [STX]sRA displayLanguage 1[ETX] |
| Write Variable: | [STX]sWN displayLanguage 1[ETX] |
| Write Variable Response: | [STX]sWA displayLanguage[ETX] |

3.1.3.4 General

3.1.3.4.1 Method: resetParamAndReboot [factory settings: reset and reboot]

The following section contains a detailed description of the method resetParamAndReboot.

Method Overview

| Method Name | Description |
|---------------------|--------------------------------------|
| resetParamAndReboot | reset the parametrization and reboot |
| Invocation Access | AuthorizedClient, Service |
| Return Values | |
| Successful | |
| Bool | |
| Value Range | False, True |
| Initialisation | False |

Method Telegram Syntax

| Method Invocation: | | | | |
|-------------------------|---------------------|--------|---------------|--------------------------------------|
| sMN resetParamAndReboot | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sMN | String | 3 | Request (SOPAS Method by Name) |
| Command | resetParamAndReboot | String | 19 | reset the parametrization and reboot |

| Method Return Value: | | | | |
|--------------------------------------|---------------------|--------|---------------|--------------------------------------|
| sAN resetParamAndReboot <Successful> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sAN | String | 3 | Result (SOPAS Method Result) |
| Command | resetParamAndReboot | String | 19 | reset the parametrization and reboot |
| Return Value 1 | Successful | Bool | 1 | |

Method Telegram Examples

| Example: Default Values | |
|---|---------------------------------------|
| Method telegram examples with parameter data and return value data set to default values. | |
| Method Invocation: | [STX] sMN resetParamAndReboot [ETX] |
| Method Return Value: | [STX] sAN resetParamAndReboot 0 [ETX] |

3.1.4 Communication

3.1.4.1 SSI

3.1.4.1.1 Variable: spdOutputMode [serial interface: select RS-422 or SSI]

The following section contains a detailed description of the variable spdOutputMode.

Variable Overview

| Variable Name | | |
|---------------|---------------------------|-------------|
| spdOutputMode | | |
| Read-Access | Always | |
| Write-Access | AuthorizedClient, Service | |
| Enum8 | | |
| Default Value | RS422 | |
| Value | Name | Description |
| 0 | SSI | |
| 1 | RS422 | |

Variable Telegram Syntax

Read Variable:

sRN spdOutputMode

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|---------------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | spdOutputMode | String | 13 | |

Read Variable Response:

sRA spdOutputMode <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|---------------|--------|---------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | spdOutputMode | String | 13 | |
| Variable Data | data | Enum8 | 1 | |

Write Variable:

sWN spdOutputMode <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|---------------|--------|---------------|------------------------------|
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | spdOutputMode | String | 13 | |
| Variable Data | data | Enum8 | 1 | |

Write Variable Response:

sWA spdOutputMode

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|---------------|--------|---------------|----------------------------------|
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | spdOutputMode | String | 13 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|--------------------------|---------------------------------|
| Read Variable: | [STX] sRN spdOutputMode [ETX] |
| Read Variable Response: | [STX] sRA spdOutputMode 1 [ETX] |
| Write Variable: | [STX] sWN spdOutputMode 1 [ETX] |
| Write Variable Response: | [STX] sWA spdOutputMode [ETX] |

3.1.4.1.2 Variable: serialOutputDistanceScale [distance value resolution for SSI data transfer: free input]

The following section contains a detailed description of the variable serialOutputDistanceScale.

Variable Overview

| Variable Name | Description |
|---------------------------|---------------------------|
| serialOutputDistanceScale | Distance scale in um |
| Read-Access | Always |
| Write-Access | AuthorizedClient, Service |

| UDInt | |
|----------------|------------|
| Value Range | 1..1000000 |
| Initialisation | 1000 |

Variable Telegram Syntax

Read Variable:

sRN serialOutputDistanceScale

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|---------------------------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | serialOutputDistanceScale | String | 25 | Distance scale in um |

Read Variable Response:

```
sRA serialOutputDistanceScale <data>
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|---------------------------|--------|---------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | serialOutputDistanceScale | String | 25 | Distance scale in um |
| Variable Data | data | UDInt | 4 | |

Write Variable:

```
sWN serialOutputDistanceScale <data>
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|---------------------------|--------|---------------|------------------------------|
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | serialOutputDistanceScale | String | 25 | Distance scale in um |
| Variable Data | data | UDInt | 4 | |

Write Variable Response:

```
sWA serialOutputDistanceScale
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|---------------------------|--------|---------------|----------------------------------|
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | serialOutputDistanceScale | String | 25 | Distance scale in um |

Variable Telegram Examples**Example: Default Values**

Variable telegram examples with data set to default values.

| | |
|---------------------------------|---|
| Read Variable: | [STX]sRN serialOutputDistanceScale[ETX] |
| Read Variable Response: | [STX]sRA serialOutputDistanceScale 3E8[ETX] |
| Write Variable: | [STX]sWN serialOutputDistanceScale 3E8[ETX] |
| Write Variable Response: | [STX]sWA serialOutputDistanceScale[ETX] |

3.1.4.1.3 Variable: ssiProtocol [SSI coding]

The following section contains a detailed description of the variable ssiProtocol.

Variable Overview

| Variable Name | Description |
|---------------|----------------------|
| ssiProtocol | selects SSI protocol |

| | |
|--------------|---------------------------|
| Read-Access | Always |
| Write-Access | AuthorizedClient, Service |

| Enum8 | | | |
|---------------|-----------|--|--|
| Default Value | D24G_E | | |
| Value | Name | Description | |
| 0 | D24D | Distance 24 bit dual, no error bit | |
| 1 | D25D | Distance 25 bit dual, no error bit | |
| 2 | D24D_E | Distance 24 bit dual, with error bit | |
| 3 | S7_D24D_E | Status 7 Bit, Distance 24 bit dual, with error bit | |
| 4 | D24G | Distance 24 bit gray, no error bit | |
| 5 | D25G | Distance 25 bit gray, no error bit | |
| 6 | D24G_E | Distance 24 bit gray, with error bit | |
| 7 | S7_D24G_E | Status 7 Bit, Distance 24 bit gray, with error bit | |

Variable Telegram Syntax**Read Variable:**

```
sRN ssiProtocol
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-------------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | ssiProtocol | String | 11 | selects SSI protocol |

| Read Variable Response: | | | | |
|--------------------------------|-----------------|-------------|----------------------|---------------------------------|
| sRA ssiProtocol <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | ssiProtocol | String | 11 | selects SSI protocol |
| Variable Data | data | Enum8 | 1 | |

| Write Variable: | | | | |
|------------------------|-----------------|-------------|----------------------|------------------------------|
| sWN ssiProtocol <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | ssiProtocol | String | 11 | selects SSI protocol |
| Variable Data | data | Enum8 | 1 | |

| Write Variable Response: | | | | |
|---------------------------------|-----------------|-------------|----------------------|----------------------------------|
| sWA ssiProtocol | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | ssiProtocol | String | 11 | selects SSI protocol |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|---------------------------------|-----------------------------|
| Read Variable: | [STX]sRN ssiProtocol[ETX] |
| Read Variable Response: | [STX]sRA ssiProtocol 6[ETX] |
| Write Variable: | [STX]sWN ssiProtocol 6[ETX] |
| Write Variable Response: | [STX]sWA ssiProtocol[ETX] |

3.1.4.2 RS422

3.1.4.2.1 Variable: spdOutputMode [serial interface: select RS-422 or SSI]

The following section contains a detailed description of the variable `spdOutputMode`.

Variable Overview

| Variable Name | | |
|----------------------|---------------------------|-------------|
| spdOutputMode | | |
| | | |
| Read-Access | Always | |
| Write-Access | AuthorizedClient, Service | |
| Enum8 | | |
| Default Value | RS422 | |
| Value | Name | Description |
| 0 | SSI | |
| 1 | RS422 | |

Variable Telegram Syntax

| Read Variable: | | | | |
|-----------------------|-----------------|-------------|----------------------|-----------------------------|
| sRN spdOutputMode | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | spdOutputMode | String | 13 | |

Read Variable Response:

```
sRA spdOutputMode <data>
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|---------------|--------|---------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | spdOutputMode | String | 13 | |
| Variable Data | data | Enum8 | 1 | |

Write Variable:

```
sWN spdOutputMode <data>
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|---------------|--------|---------------|------------------------------|
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | spdOutputMode | String | 13 | |
| Variable Data | data | Enum8 | 1 | |

Write Variable Response:

```
sWA spdOutputMode
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|---------------|--------|---------------|----------------------------------|
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | spdOutputMode | String | 13 | |

Variable Telegram Examples**Example: Default Values**

Variable telegram examples with data set to default values.

| | |
|---------------------------------|-------------------------------|
| Read Variable: | [STX]sRN spdOutputMode[ETX] |
| Read Variable Response: | [STX]sRA spdOutputMode 1[ETX] |
| Write Variable: | [STX]sWN spdOutputMode 1[ETX] |
| Write Variable Response: | [STX]sWA spdOutputMode[ETX] |

3.1.4.2.2 Variable: serialOutputDistanceScale [distance value resolution for RS-422 data transfer: free input]]

The following section contains a detailed description of the variable serialOutputDistanceScale.

Variable Overview

| Variable Name | Description |
|---------------------------|---------------------------|
| serialOutputDistanceScale | Distance scale in um |
| Read-Access | Always |
| Write-Access | AuthorizedClient, Service |
| UDInt | |
| Value Range | 1..1000000 |
| Initialisation | 1000 |

Variable Telegram Syntax**Read Variable:**

```
sRN serialOutputDistanceScale
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|---------------------------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | serialOutputDistanceScale | String | 25 | Distance scale in um |

Read Variable Response:

```
sRA serialOutputDistanceScale <data>
```

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|---------------------------|--------|---------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | serialOutputDistanceScale | String | 25 | Distance scale in um |
| Variable Data | data | UDInt | 4 | |

| Write Variable: | | | | |
|--------------------------------------|---------------------------|-------------|----------------------|------------------------------|
| sWN serialOutputDistanceScale <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | serialOutputDistanceScale | String | 25 | Distance scale in um |
| Variable Data | data | UDInt | 4 | |

| Write Variable Response: | | | | |
|---------------------------------|---------------------------|-------------|----------------------|----------------------------------|
| sWA serialOutputDistanceScale | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | serialOutputDistanceScale | String | 25 | Distance scale in um |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|---------------------------------|---|
| Read Variable: | [STX]sRN serialOutputDistanceScale[ETX] |
| Read Variable Response: | [STX]sRA serialOutputDistanceScale 3E8[ETX] |
| Write Variable: | [STX]sWN serialOutputDistanceScale 3E8[ETX] |
| Write Variable Response: | [STX]sWA serialOutputDistanceScale[ETX] |

3.1.4.2.3 Variable: serialOutputVelocityScale [speed value resolution for RS-422 data transfer: free input]

The following section contains a detailed description of the variable serialOutputVelocityScale.

Variable Overview

| Variable Name | Description |
|---------------------------|---------------------------|
| serialOutputVelocityScale | Velocity scale in um/s |
| Read-Access | Always |
| Write-Access | AuthorizedClient, Service |
| UDInt | |
| Value Range | 1..1000000 |
| Initialisation | 1000 |

Variable Telegram Syntax

Read Variable:

sRN serialOutputVelocityScale

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|---------------------------|-------------|----------------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | serialOutputVelocityScale | String | 25 | Velocity scale in um/s |

Read Variable Response:

sRA serialOutputVelocityScale <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|---------------------------|-------------|----------------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | serialOutputVelocityScale | String | 25 | Velocity scale in um/s |
| Variable Data | data | UDInt | 4 | |

Write Variable:

sWN serialOutputVelocityScale <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|---------------------------|-------------|----------------------|------------------------------|
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | serialOutputVelocityScale | String | 25 | Velocity scale in um/s |
| Variable Data | data | UDInt | 4 | |

Write Variable Response:

sWA serialOutputVelocityScale

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|---------------------------|--------|---------------|----------------------------------|
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | serialOutputVelocityScale | String | 25 | Velocity scale in um/s |

Variable Telegram Examples**Example: Default Values**

Variable telegram examples with data set to default values.

| | |
|--------------------------|---|
| Read Variable: | [STX]sRN serialOutputVelocityScale[ETX] |
| Read Variable Response: | [STX]sRA serialOutputVelocityScale 3E8[ETX] |
| Write Variable: | [STX]sWN serialOutputVelocityScale 3E8[ETX] |
| Write Variable Response: | [STX]sWA serialOutputVelocityScale[ETX] |

3.1.4.2.4 Variable: rs422PeriodicOutputContent [continuous RS-422 output]

The following section contains a detailed description of the variable rs422PeriodicOutputContent.

Variable Overview

| Variable Name | Description | | |
|----------------------------|--|-------------|--|
| rs422PeriodicOutputContent | Select what to output periodically; nothing (periodic output disabled), only distance, distance and velocity or distance and status. | | |
| Read-Access | Always | | |
| Write-Access | AuthorizedClient, Service | | |
| Enum8 | | | |
| Default Value | OFF | | |
| Value | Name | Description | |
| 0 | OFF | | |
| 1 | DISTANCE | | |
| 2 | DISTANCE_VELOCITY | | |
| 3 | DISTANCE_STATUS | | |
| 4 | DISTANCE_RSSI | | |

Variable Telegram Syntax**Read Variable:**

sRN rs422PeriodicOutputContent

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------------------------|--------|---------------|--|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | rs422PeriodicOutputContent | String | 26 | Select what to output periodically; nothing (periodic output disabled), only distance, distance and velocity or distance and status. |

Read Variable Response:

sRA rs422PeriodicOutputContent <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------------------------|--------|---------------|--|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | rs422PeriodicOutputContent | String | 26 | Select what to output periodically; nothing (periodic output disabled), only distance, distance and velocity or distance and status. |
| Variable Data | data | Enum8 | 1 | |

Write Variable:

sWN rs422PeriodicOutputContent <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------------------------|--------|---------------|--|
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | rs422PeriodicOutputContent | String | 26 | Select what to output periodically; nothing (periodic output disabled), only distance, distance and velocity or distance and status. |
| Variable Data | data | Enum8 | 1 | |

| Write Variable Response: | | | | |
|---------------------------------|----------------------------|-------------|----------------------|--|
| sWA rs422PeriodicOutputContent | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | rs422PeriodicOutputContent | String | 26 | Select what to output periodically; nothing (periodic output disabled), only distance, distance and velocity or distance and status. |

Variable Telegram Examples

| Example: Default Values | |
|---|--|
| Variable telegram examples with data set to default values. | |
| Read Variable: | [STX]sRN rs422PeriodicOutputContent[ETX] |
| Read Variable Response: | [STX]sRA rs422PeriodicOutputContent 0[ETX] |
| Write Variable: | [STX]sWN rs422PeriodicOutputContent 0[ETX] |
| Write Variable Response: | [STX]sWA rs422PeriodicOutputContent[ETX] |

3.1.4.2.5 Variable: rs422PeriodicOutputFormat [RS-422 data protocol]

The following section contains a detailed description of the variable rs422PeriodicOutputFormat.

Variable Overview

| Variable Name | Description | |
|---------------------------|---|-------------|
| rs422PeriodicOutputFormat | Select format/framing used for periodic output; SerialLink or CR/LF protocol. | |
| Read-Access | Always | |
| Write-Access | AuthorizedClient, Service | |
| Enum8 | | |
| Default Value | CRLF | |
| Value | Name | Description |
| 0 | SERIAL_LINK | |
| 1 | CRLF | |

Variable Telegram Syntax

| Read Variable: | | | | |
|--------------------------------------|---------------------------|-------------|----------------------|---|
| sRN rs422PeriodicOutputFormat | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | rs422PeriodicOutputFormat | String | 25 | Select format/framing used for periodic output; SerialLink or CR/LF protocol. |
| Read Variable Response: | | | | |
| sRA rs422PeriodicOutputFormat <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | rs422PeriodicOutputFormat | String | 25 | Select format/framing used for periodic output; SerialLink or CR/LF protocol. |
| Variable Data | data | Enum8 | 1 | |
| Write Variable: | | | | |
| sWN rs422PeriodicOutputFormat <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | rs422PeriodicOutputFormat | String | 25 | Select format/framing used for periodic output; SerialLink or CR/LF protocol. |
| Variable Data | data | Enum8 | 1 | |

| Write Variable Response: | | | | |
|---------------------------------|---------------------------|-------------|----------------------|---|
| sWA rs422PeriodicOutputFormat | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | rs422PeriodicOutputFormat | String | 25 | Select format/framing used for periodic output; SerialLink or CR/LF protocol. |

Variable Telegram Examples

| Example: Default Values | |
|---|---|
| Variable telegram examples with data set to default values. | |
| Read Variable: | [STX]sRN rs422PeriodicOutputFormat[ETX] |
| Read Variable Response: | [STX]sRA rs422PeriodicOutputFormat 1[ETX] |
| Write Variable: | [STX]sWN rs422PeriodicOutputFormat 1[ETX] |
| Write Variable Response: | [STX]sWA rs422PeriodicOutputFormat[ETX] |

3.1.4.2.6 Variable: rs422PeriodicDuration [RS-422 output cycle time]

The following section contains a detailed description of the variable rs422PeriodicDuration.

Variable Overview

| Variable Name | Description |
|-----------------------|--|
| rs422PeriodicDuration | Cycle duration of periodic output in ms; set to 0 to output as fast as possible. |
| Read-Access | Always |
| Write-Access | AuthorizedClient, Service |
| UDInt | |
| Value Range | 0..1000 |
| Initialisation | 1 |

Variable Telegram Syntax

| Read Variable: | | | | |
|----------------------------------|-----------------------|-------------|----------------------|--|
| sRN rs422PeriodicDuration | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | rs422PeriodicDuration | String | 21 | Cycle duration of periodic output in ms; set to 0 to output as fast as possible. |
| Read Variable Response: | | | | |
| sRA rs422PeriodicDuration <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | rs422PeriodicDuration | String | 21 | Cycle duration of periodic output in ms; set to 0 to output as fast as possible. |
| Variable Data | data | UDInt | 4 | |
| Write Variable: | | | | |
| sWN rs422PeriodicDuration <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Write Variable: | | | | |
| sWN rs422PeriodicDuration <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command | rs422PeriodicDuration | String | 21 | Cycle duration of periodic output in ms; set to 0 to output as fast as possible. |
| Variable Data | data | UDInt | 4 | |

| Write Variable Response: | | | | |
|---------------------------------|-----------------------|-------------|----------------------|--|
| sWA rs422PeriodicDuration | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | rs422PeriodicDuration | String | 21 | Cycle duration of periodic output in ms; set to 0 to output as fast as possible. |

Variable Telegram Examples

| Example: Default Values | |
|---|---------------------------------------|
| Variable telegram examples with data set to default values. | |
| Read Variable: | [STX]sRN rs422PeriodicDuration[ETX] |
| Read Variable Response: | [STX]sRA rs422PeriodicDuration 1[ETX] |
| Write Variable: | [STX]sWN rs422PeriodicDuration 1[ETX] |
| Write Variable Response: | [STX]sWA rs422PeriodicDuration[ETX] |

3.1.4.2.7 Variable: rs422BaudRate [RS-422 data transmission rate]

The following section contains a detailed description of the variable rs422BaudRate.

Variable Overview

| Variable Name | | |
|----------------------|---------------------------|-------------|
| rs422BaudRate | | |
| | | |
| Read-Access | Always | |
| Write-Access | AuthorizedClient, Service | |
| Enum8 | | |
| Value | Name | Description |
| | 4800 | |
| | 9600 | |
| | 19200 | |
| | 38400 | |
| | 57600 | |
| | 115200 | |
| | 230400 | |

Variable Telegram Syntax

| Read Variable: | | | | |
|-----------------------|-----------------|-------------|----------------------|-----------------------------|
| sRN rs422BaudRate | | | | |
| | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | rs422BaudRate | String | 13 | |

| Read Variable Response: | | | | |
|--------------------------------|-----------------|-------------|----------------------|---------------------------------|
| sRA rs422BaudRate <data> | | | | |
| | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | rs422BaudRate | String | 13 | |
| Variable Data | data | Enum8 | 1 | |

| Write Variable: | | | | |
|--------------------------|-----------------|-------------|----------------------|------------------------------|
| sWN rs422BaudRate <data> | | | | |
| | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | rs422BaudRate | String | 13 | |
| Variable Data | data | Enum8 | 1 | |

Write Variable Response:

sWA rs422BaudRate

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|---------------|--------|---------------|----------------------------------|
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | rs422BaudRate | String | 13 | |

Variable Telegram Examples**Example: Default Values**

Variable telegram examples with data set to default values.

| | |
|--------------------------|-----------------------------|
| Read Variable: | [STX]sRN_rs422BaudRate[ETX] |
| Read Variable Response: | [STX]sRA_rs422BaudRate[ETX] |
| Write Variable: | [STX]sWN_rs422BaudRate[ETX] |
| Write Variable Response: | [STX]sWA_rs422BaudRate[ETX] |

3.1.4.2.8 Variable: rs422ByteFormat [RS-422 data format]

The following section contains a detailed description of the variable rs422ByteFormat.

Variable Overview

| Variable Name |
|-----------------|
| rs422ByteFormat |

| | |
|--------------|---------------------------|
| Read-Access | Always |
| Write-Access | AuthorizedClient, Service |

Enum8

| Value | Name | Description |
|-------|------|-------------|
| 0 | 7N1 | |
| 1 | 7O1 | |
| 2 | 7E1 | |
| 3 | 8N1 | |
| 4 | 8O1 | |
| 5 | 8E1 | |

Variable Telegram Syntax**Read Variable:**

sRN rs422ByteFormat

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | rs422ByteFormat | String | 15 | |

Read Variable Response:

sRA rs422ByteFormat <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------------|--------|---------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | rs422ByteFormat | String | 15 | |
| Variable Data | data | Enum8 | 1 | |

Write Variable:

sWN rs422ByteFormat <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------------|--------|---------------|------------------------------|
| Command Type | sWN | String | 3 | Write SOPAS Variable by Name |
| Command | rs422ByteFormat | String | 15 | |
| Variable Data | data | Enum8 | 1 | |

Write Variable Response:

sWA rs422ByteFormat

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------------|--------|---------------|----------------------------------|
| Command Type | sWA | String | 3 | SOPAS Variable Write Acknowledge |
| Command | rs422ByteFormat | String | 15 | |

Variable Telegram Examples**Example: Default Values**

Variable telegram examples with data set to default values.

| | |
|---------------------------------|---------------------------------|
| Read Variable: | [STX]sRN rs422ByteFormat[ETX] |
| Read Variable Response: | [STX]sRA rs422ByteFormat 0[ETX] |
| Write Variable: | [STX]sWN rs422ByteFormat 0[ETX] |
| Write Variable Response: | [STX]sWA rs422ByteFormat[ETX] |

3.1.5 Info

3.1.5.1 Device

3.1.5.1.1 Variable: hwUpdateNumber [hardware revision of sensor]

The following section contains a detailed description of the variable hwUpdateNumber.

Variable Overview

| Variable Name | Description |
|-------------------|------------------------|
| hwUpdateNumber | Hardware Update Number |
| Read-Access | Always |
| Write-Access | No! (readonly) |
| FlexString | |
| Length | 0..8 |
| Initialisation | 00000000 |

Variable Telegram Syntax**Read Variable:**

sRN hwUpdateNumber

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | hwUpdateNumber | String | 14 | Hardware Update Number |

Read Variable Response:

sRA hwUpdateNumber <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------------|------------|---------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | hwUpdateNumber | String | 14 | Hardware Update Number |
| Variable Data | data | FlexString | 8 | |

Variable Telegram Examples**Example: Default Values**

Variable telegram examples with data set to default values.

| | |
|--------------------------------|---|
| Read Variable: | [STX]sRN hwUpdateNumber[ETX] |
| Read Variable Response: | [STX]sRA hwUpdateNumber 8 00000000[ETX] |

3.1.5.1.2 Variable: productPartNo [part number of sensor]

The following section contains a detailed description of the variable productPartNo.

Variable Overview

| Variable Name | Description |
|-------------------|---------------------|
| productPartNo | Product Part Number |
| Read-Access | No! (writeonly) |
| Write-Access | No! (readonly) |
| FlexString | |
| Length | 0..7 |
| Initialisation | 0000000 |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

3.1.5.1.3 Variable: SerialNumber [serial number of sensor]

The following section contains a detailed description of the variable SerialNumber.

Variable Overview

| Variable Name | Description |
|-------------------|-------------------------|
| SerialNumber | serial number of device |
| Read-Access | Always |
| Write-Access | No! (readonly) |
| FlexString | |
| Length | 0..8 |
| Initialisation | 12345678 |

Read Variable:

sRN SerialNumber

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|--------------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | SerialNumber | String | 12 | serial number of device |

Read Variable Response:

sRA SerialNumber <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|--------------|------------|---------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | SerialNumber | String | 12 | serial number of device |
| Variable Data | data | FlexString | 8 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

Read Variable: [STX]sRN SerialNumber[ETX]

Read Variable Response: [STX]sRA SerialNumber 8 12345678[ETX]

3.1.5.1.4 Variable: productCode [product code/type of sensor]

The following section contains a detailed description of the variable productCode.

Variable Overview

| Variable Name | Description |
|---------------|--------------|
| productCode | Product Code |

| | |
|--------------|----------------|
| Read-Access | Always |
| Write-Access | No! (readonly) |

| FlexString | |
|----------------|---------------|
| Length | 0..18 |
| Initialisation | Dx1000-S11101 |

Read Variable:

sRN productCode

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-------------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | productCode | String | 11 | Product Code |

Read Variable Response:

sRA productCode <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-------------|------------|---------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | productCode | String | 11 | Product Code |
| Variable Data | data | FlexString | 18 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|-------------------------|---|
| Read Variable: | [STX]sRN productCode[ETX] |
| Read Variable Response: | [STX]sRA productCode D Dx1000-S11101[ETX] |

3.1.5.1.5 Variable: interfaceVersion [interface revision]

The following section contains a detailed description of the variable interfaceVersion.

Variable Overview

| Variable Name | Description |
|------------------|--|
| interfaceVersion | Interface Version of application controller: version.subversion.revision.build |

| | |
|--------------|----------------|
| Read-Access | Always |
| Write-Access | No! (readonly) |

| FlexString | |
|----------------|-------------|
| Length | 0..11 |
| Initialisation | 000.000.000 |

Read Variable:

sRN interfaceVersion

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|------------------|--------|---------------|--|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | interfaceVersion | String | 16 | Interface Version of application controller: version.subversion.revision.build |

| Read Variable Response: | | | | |
|--------------------------------|------------------|-------------|----------------------|---|
| sRA interfaceVersion <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | interfaceVersion | String | 16 | Interface Version of application controller: version.subversion.revision.build |
| Variable Data | data | FlexString | 11 | |

Variable Telegram Examples

| Example: Default Values | |
|---|--|
| Variable telegram examples with data set to default values. | |
| Read Variable: | [STX]sRN interfaceVersion[ETX] |
| Read Variable Response: | [STX]sRA interfaceVersion B 000.000.000[ETX] |

3.1.5.1.6 Variable: firmwareBuildTime [Firmware: created on]

The following section contains a detailed description of the variable `firmwareBuildTime`.

Variable Overview

| Variable Name | Description |
|----------------------|---------------------|
| firmwareBuildTime | Firmware Build Time |
| Read-Access | Always |
| Write-Access | No! (readonly) |
| FlexString | |
| Length | 0..21 |
| Initialisation | 2015/01/01 00:00:00 |

Read Variable:

sRN firmwareBuildTime

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-------------------|-------------|----------------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | firmwareBuildTime | String | 17 | Firmware Build Time |

Read Variable Response:

sRA firmwareBuildTime <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-------------------|-------------|----------------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | firmwareBuildTime | String | 17 | Firmware Build Time |
| Variable Data | data | FlexString | 21 | |

Variable Telegram Examples

| Example: Default Values | |
|---|--|
| Variable telegram examples with data set to default values. | |
| Read Variable: | [STX]sRN firmwareBuildTime[ETX] |
| Read Variable Response: | [STX]sRA firmwareBuildTime 13 2015/01/01 00:00:00[ETX] |

3.1.5.1.7 Variable: firmwareVerification [firmware verification]

The following section contains a detailed description of the variable `firmwareVerification`.

Variable Overview

| Variable Name | Description |
|----------------------|---|
| firmwareVerification | Hash value computed over all firmware vectors |
| Read-Access | Always |
| Write-Access | No! (readonly) |

| FlexString | |
|-------------------|---------------------|
| Length | 0..19 |
| Initialisation | 0000-0000-0000-0000 |

| Read Variable: | |
|--------------------------|--|
| sRN firmwareVerification | |

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|----------------------|-------------|----------------------|---|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | firmwareVerification | String | 20 | Hash value computed over all firmware vectors |

| Read Variable Response: | |
|---------------------------------|----------------------|
| sRA firmwareVerification <data> | |
| Telegram Part | Telegram |
| Command Type | sRA |
| Command | firmwareVerification |
| Variable Data | data |
| | FlexString |
| | 19 |

Variable Telegram Examples

| Example: Default Values | |
|---|---|
| Variable telegram examples with data set to default values. | |
| Read Variable: | [STX]sRN firmwareVerification[ETX] |
| Read Variable Response: | [STX]sRA firmwareVerification 13 0000-0000-0000-0000[ETX] |

3.1.5.2 IOs

3.1.5.2.1 Variable: eventCntIo1 [IO counter: In1/Q1]

The following section contains a detailed description of the variable eventCntIo1.

Variable Overview

| Variable Name | Description |
|----------------------|---------------------------|
| eventCntIo1 | Event counter of IO 1 |
| Read-Access | AuthorizedClient, Service |
| Write-Access | No! (readonly) |
| UDInt | |
| Value Range | 0..4294967295 |
| Initialisation | 0 |

Variable Telegram Syntax

| Read Variable: | |
|--------------------------------|-----------------------|
| sRN eventCntIo1 | |
| Telegram Part | Telegram |
| Command Type | sRN |
| Command | eventCntIo1 |
| | String |
| | 11 |
| | Event counter of IO 1 |
| Read Variable Response: | |
| sRA eventCntIo1 <data> | |
| Telegram Part | Telegram |
| Command Type | sRA |
| Command | eventCntIo1 |
| Variable Data | data |
| | UDInt |
| | 4 |

Variable Telegram Examples

| Example: Default Values | |
|---|-----------------------------|
| Variable telegram examples with data set to default values. | |
| Read Variable: | [STX]sRN eventCntIo1[ETX] |
| Read Variable Response: | [STX]sRA eventCntIo1 0[ETX] |

3.1.5.2.2 Variable: eventCntIo2 [IO counter: Q2]

The following section contains a detailed description of the variable eventCntIo2.

Variable Overview

| Variable Name | Description |
|----------------|---------------------------|
| eventCntIo2 | Event counter of IO 2 |
| Read-Access | AuthorizedClient, Service |
| Write-Access | No! (readonly) |
| UDInt | |
| Value Range | 0..4294967295 |
| Initialisation | 0 |

Variable Telegram Syntax

| Read Variable: | | | | |
|-------------------------|-------------|--------|---------------|-----------------------------|
| sRN eventCntIo2 | | | | |
| Read Variable Response: | | | | |
| sRA eventCntIo2 <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | eventCntIo2 | String | 11 | Event counter of IO 2 |
| Variable Data | data | UDInt | 4 | |

Variable Telegram Examples

| Example: Default Values | |
|---|-----------------------------|
| Variable telegram examples with data set to default values. | |
| Read Variable: | [STX]sRN eventCntIo2[ETX] |
| Read Variable Response: | [STX]sRA eventCntIo2 0[ETX] |

3.1.5.2.3 Variable: eventCntIo3 [IO counter: Q3]

The following section contains a detailed description of the variable eventCntIo3.

Variable Overview

| Variable Name | Description |
|----------------|---------------------------|
| eventCntIo3 | Event counter of IO 3 |
| Read-Access | AuthorizedClient, Service |
| Write-Access | No! (readonly) |
| UDInt | |
| Value Range | 0..4294967295 |
| Initialisation | 0 |

Variable Telegram Syntax

| Read Variable: | | | | |
|-------------------------|-------------|--------|---------------|-----------------------------|
| sRN eventCntIo3 | | | | |
| Read Variable Response: | | | | |
| sRA eventCntIo3 <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | eventCntIo3 | String | 11 | Event counter of IO 3 |
| Variable Data | data | UDInt | 4 | |

| Read Variable Response: | | | | |
|--------------------------------|-----------------|-------------|----------------------|---------------------------------|
| sRA eventCntIo3 <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | eventCntIo3 | String | 11 | Event counter of IO 3 |
| Variable Data | data | UDInt | 4 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|--------------------------------|-----------------------------|
| Read Variable: | [STX]sRN eventCntIo3[ETX] |
| Read Variable Response: | [STX]sRA eventCntIo3_0[ETX] |

3.1.5.2.4 Variable: eventCntIo4 [IO counter: Q4]

The following section contains a detailed description of the variable eventCntIo4.

Variable Overview

| Variable Name | Description |
|----------------------|---------------------------|
| eventCntIo4 | Event counter of IO 4 |
| Read-Access | AuthorizedClient, Service |
| Write-Access | No! (readonly) |
| UDInt | |
| Value Range | 0..4294967295 |
| Initialisation | 0 |

Variable Telegram Syntax

Read Variable:

sRN eventCntIo4

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------|----------------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | eventCntIo4 | String | 11 | Event counter of IO 4 |

Read Variable Response:

sRA eventCntIo4 <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------|----------------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | eventCntIo4 | String | 11 | Event counter of IO 4 |
| Variable Data | data | UDInt | 4 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|--------------------------------|-----------------------------|
| Read Variable: | [STX]sRN eventCntIo4[ETX] |
| Read Variable Response: | [STX]sRA eventCntIo4_0[ETX] |

3.1.5.2.5 Variable: eventCntIo5 [IO counter: In2]

The following section contains a detailed description of the variable eventCntIo5.

Variable Overview

| Variable Name | Description |
|----------------------|---------------------------|
| eventCntIo5 | Event counter of IO 5 |
| Read-Access | AuthorizedClient, Service |
| Write-Access | No! (readonly) |

| UDInt | |
|----------------|---------------|
| Value Range | 0..4294967295 |
| Initialisation | 0 |

Variable Telegram Syntax

Read Variable:

sRN eventCntIo5

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------|----------------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | eventCntIo5 | String | 11 | Event counter of IO 5 |

Read Variable Response:

sRA eventCntIo5 <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------|----------------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | eventCntIo5 | String | 11 | Event counter of IO 5 |
| Variable Data | data | UDInt | 4 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|-----------------------|---------------------------|
| Read Variable: | [STX]sRN eventCntIo5[ETX] |
|-----------------------|---------------------------|

| | |
|--------------------------------|-----------------------------|
| Read Variable Response: | [STX]sRA eventCntIo5 0[ETX] |
|--------------------------------|-----------------------------|

3.1.5.2.6 Method: resetEventCounters [deleting the counter readings of switching events/reset]

The following section contains a detailed description of the method resetEventCounters.

Method Overview

| Method Name | Description |
|--------------------|-----------------------------|
| resetEventCounters | Reset the IO event counters |
| Invocation Access | Always |

Method Telegram Syntax

Method Invocation:

sMN resetEventCounters

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|--------------------|-------------|----------------------|--------------------------------|
| Command Type | sMN | String | 3 | Request (SOPAS Method by Name) |
| Command | resetEventCounters | String | 18 | Reset the IO event counters |

Method Return Value:

sAN resetEventCounters

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|--------------------|-------------|----------------------|------------------------------|
| Command Type | sAN | String | 3 | Result (SOPAS Method Result) |
| Command | resetEventCounters | String | 18 | Reset the IO event counters |

Method Telegram Examples

Example: Default Values

Method telegram examples with parameter data and return value data set to default values.

| | |
|---------------------------|----------------------------------|
| Method Invocation: | [STX]sMN resetEventCounters[ETX] |
|---------------------------|----------------------------------|

| | |
|-----------------------------|----------------------------------|
| Method Return Value: | [STX]sAN resetEventCounters[ETX] |
|-----------------------------|----------------------------------|

3.2 Measurement

3.2.1 Variable: Distance [measured distance to object]

The following section contains a detailed description of the variable Distance.

Variable Overview

| Variable Name | Description |
|----------------|-------------------------|
| Distance | Distance in mm |
| Read-Access | Always |
| Write-Access | No! (readonly) |
| DInt | |
| Value Range | -2147483648..2147483647 |
| Initialisation | 0 |
| Physical Unit | mm |

Variable Telegram Syntax

Read Variable:

sRN Distance

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | Distance | String | 8 | Distance in mm |

Read Variable Response:

sRA Distance <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------|--------|---------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | Distance | String | 8 | Distance in mm |
| Variable Data | data | DInt | 4 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

Read Variable: [STX] sRN Distance[ETX]

Read Variable Response: [STX] sRA Distance 0[ETX]

3.2.2 Variable: DistanceF [measured distance to object]

The following section contains a detailed description of the variable DistanceF.

Variable Overview

| Variable Name | Description |
|----------------|----------------------------|
| DistanceF | Distance in mm (float) |
| Read-Access | Always |
| Write-Access | No! (readonly) |
| Real | |
| Value Range | See specification IEEE 754 |
| Initialisation | 0 |
| Physical Unit | mm |

Variable Telegram Syntax

Read Variable:

sRN DistanceF

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | DistanceF | String | 9 | Distance in mm (float) |

| Read Variable Response: | | | | |
|--------------------------------|-----------------|-------------|----------------------|---------------------------------|
| sRA DistanceF <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | DistanceF | String | 9 | Distance in mm (float) |
| Variable Data | data | Real | 4 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|--------------------------------|----------------------------------|
| Read Variable: | [STX]sRN_DistanceF[ETX] |
| Read Variable Response: | [STX]sRA_DistanceF 00000000[ETX] |

3.2.3 Variable: Velocity [measured object speed]

The following section contains a detailed description of the variable Velocity.

Variable Overview

| Variable Name | Description |
|----------------------|-------------------------|
| Velocity | Velocity in mm / s |
| Read-Access | Always |
| Write-Access | No! (readonly) |
| DInt | |
| Value Range | -2147483648..2147483647 |
| Initialisation | 0 |
| Physical Unit | mm/s |

Variable Telegram Syntax

Read Variable:

sRN Velocity

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------|----------------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | Velocity | String | 8 | Velocity in mm / s |

Read Variable Response:

sRA Velocity <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------|----------------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | Velocity | String | 8 | Velocity in mm / s |
| Variable Data | data | DInt | 4 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|--------------------------------|--------------------------|
| Read Variable: | [STX]sRN_Velocity[ETX] |
| Read Variable Response: | [STX]sRA_Velocity 0[ETX] |

3.2.4 Variable: RSSI [measured signal level]

The following section contains a detailed description of the variable RSSI.

Variable Overview

| Variable Name | Description |
|----------------------|--------------------|
| RSSI | Rx Level |
| Read-Access | Always |
| Write-Access | No! (readonly) |

| DInt | |
|----------------|-------------------------|
| Value Range | -2147483648..2147483647 |
| Initialisation | 0 |

Variable Telegram Syntax

Read Variable:

sRN RSSI

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------|----------------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | RSSI | String | 4 | Rx Level |

Read Variable Response:

sRA RSSI <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------|----------------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | RSSI | String | 4 | Rx Level |
| Variable Data | data | DInt | 4 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

Read Variable: [STX]sRN RSSI [ETX]

Read Variable Response: [STX]sRA RSSI 0 [ETX]

3.2.5 Variable: deviceTemperature [measured operating temperature of the device]

The following section contains a detailed description of the variable deviceTemperature.

Variable Overview

| Variable Name | Description |
|----------------------|--------------------|
| deviceTemperature | Device temperature |

| | |
|--------------|----------------|
| Read-Access | Always |
| Write-Access | No! (readonly) |

| SInt | |
|----------------|-----------|
| Value Range | -128..127 |
| Initialisation | 0 |
| Physical Unit | °C |

Variable Telegram Syntax

Read Variable:

sRN deviceTemperature

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-------------------|-------------|----------------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | deviceTemperature | String | 17 | Device temperature |

Read Variable Response:

sRA deviceTemperature <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-------------------|-------------|----------------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | deviceTemperature | String | 17 | Device temperature |
| Variable Data | data | SInt | 1 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|-----------------------|----------------------------------|
| Read Variable: | [STX] sRN deviceTemperature[ETX] |
|-----------------------|----------------------------------|

| | |
|--------------------------------|------------------------------------|
| Read Variable Response: | [STX] sRA deviceTemperature 0[ETX] |
|--------------------------------|------------------------------------|

3.2.6 Variable: OpHoursDevice [operating time display]

The following section contains a detailed description of the variable OpHoursDevice.

Variable Overview

| Variable Name | Description |
|---------------|---|
| OpHoursDevice | The total number of operating hours during the lifetime of the device. Resolution is a 1 hour |

| | |
|--------------|----------------|
| Read-Access | Always |
| Write-Access | No! (readonly) |

| UDInt | |
|----------------|---------------|
| Value Range | 0..4294967295 |
| Initialisation | 0 |
| Physical Unit | h |

Variable Telegram Syntax

Read Variable:

sRN OpHoursDevice

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|---------------|--------|---------------|---|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | OpHoursDevice | String | 13 | The total number of operating hours during the lifetime of the device. Resolution is a 1 hour |

Read Variable Response:

sRA OpHoursDevice <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|---------------|--------|---------------|---|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | OpHoursDevice | String | 13 | The total number of operating hours during the lifetime of the device. Resolution is a 1 hour |
| Variable Data | data | UDInt | 4 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|-----------------------|------------------------------|
| Read Variable: | [STX] sRN OpHoursDevice[ETX] |
|-----------------------|------------------------------|

| | |
|--------------------------------|--------------------------------|
| Read Variable Response: | [STX] sRA OpHoursDevice 0[ETX] |
|--------------------------------|--------------------------------|

3.3 Device Status Flags

3.3.1 Info

3.3.1.1 Variable: noEcho [bit 11 of status word: no echo]

The following section contains a detailed description of the variable noEcho.

Variable Overview

| Variable Name |
|---------------|
| noEcho |

| | |
|--------------|----------------|
| Read-Access | Always |
| Write-Access | No! (readonly) |

| Bool | |
|----------------|-------------|
| Value Range | False, True |
| Initialisation | False |

Variable Telegram Syntax

Read Variable:

sRN noEcho

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | noEcho | String | 6 | |

Read Variable Response:

sRA noEcho <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------|--------|---------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | noEcho | String | 6 | |
| Variable Data | data | Bool | 1 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

Read Variable: [STX]sRN_noEcho[ETX]

Read Variable Response: [STX]sRA_noEcho_0[ETX]

3.3.1.2 Variable: BridgingActive [bit 12 of status word: no echo: delay time active]

The following section contains a detailed description of the variable BridgingActive.

Variable Overview

| Variable Name | |
|----------------------|----------------|
| BridgingActive | |
| Read-Access | Always |
| Write-Access | No! (readonly) |
| Bool | |
| Value Range | False, True |
| Initialisation | False |

Variable Telegram Syntax

Read Variable:

sRN BridgingActive

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | BridgingActive | String | 14 | |

Read Variable Response:

sRA BridgingActive <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------------|--------|---------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | BridgingActive | String | 14 | |
| Variable Data | data | Bool | 1 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

Read Variable: [STX]sRN_BridgingActive[ETX]

Read Variable Response: [STX]sRA_BridgingActive_0[ETX]

3.3.1.3 Variable: laserState [bit 14 of status word: measurement laser active]

The following section contains a detailed description of the variable laserState.

Variable Overview

| Variable Name | Description |
|----------------|---|
| laserState | signals if measurement laser is on or off |
| Read-Access | Always |
| Write-Access | No! (readonly) |
| Bool | |
| Value Range | False, True |
| Initialisation | False |

Variable Telegram Syntax

| Read Variable: | | | | |
|-------------------------|------------|--------|---------------|---|
| sRN laserState | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | laserState | String | 10 | signals if measurement laser is on or off |
| Read Variable Response: | | | | |
| sRA laserState <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | laserState | String | 10 | signals if measurement laser is on or off |
| Variable Data | data | Bool | 1 | |

Variable Telegram Examples

| Example: Default Values |
|---|
| Variable telegram examples with data set to default values. |
| Read Variable: [STX] sRN laserState [ETX] |
| Read Variable Response: [STX] sRA laserState 0 [ETX] |

3.3.1.4 Variable: pilotState [bit 15 of status word: alignment laser active]

The following section contains a detailed description of the variable pilotState.

Variable Overview

| Variable Name | Description |
|----------------|-------------------------------------|
| pilotState | signals if pilot laser is on or off |
| Read-Access | Always |
| Write-Access | No! (readonly) |
| Bool | |
| Value Range | False, True |
| Initialisation | False |

Variable Telegram Syntax

| Read Variable: | | | | |
|----------------|------------|--------|---------------|-------------------------------------|
| sRN pilotState | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | pilotState | String | 10 | signals if pilot laser is on or off |

| Read Variable Response: | | | | |
|--------------------------------|-----------------|-------------|----------------------|-------------------------------------|
| sRA pilotState <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | pilotState | String | 10 | signals if pilot laser is on or off |
| Variable Data | data | Bool | 1 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|--------------------------------|----------------------------|
| Read Variable: | [STX]sRN_pilotState[ETX] |
| Read Variable Response: | [STX]sRA_pilotState_0[ETX] |

3.3.1.5 Variable: heaterStatus [bit 13 of status word: heating active]

The following section contains a detailed description of the variable heaterStatus.

Variable Overview

| Variable Name | Description |
|----------------------|--|
| heaterStatus | Signals if heater is on (1) or off (0) |
| Read-Access | Always |
| Write-Access | No! (readonly) |
| Bool | |
| Value Range | False, True |
| Initialisation | False |

Variable Telegram Syntax

Read Variable:

sRN_heaterStatus

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------|----------------------|--|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | heaterStatus | String | 12 | Signals if heater is on (1) or off (0) |

Read Variable Response:

sRA_heaterStatus <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------|----------------------|--|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | heaterStatus | String | 12 | Signals if heater is on (1) or off (0) |
| Variable Data | data | Bool | 1 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|--------------------------------|------------------------------|
| Read Variable: | [STX]sRN_heaterStatus[ETX] |
| Read Variable Response: | [STX]sRA_heaterStatus_0[ETX] |

3.3.1.6 Variable: io1state [bit 6 of status word: status (=switching state or input state) of Q1/In1]

The following section contains a detailed description of the variable io1state.

Variable Overview

| Variable Name | Description |
|----------------|---------------------------|
| io1state | State of IO 1 |
| Read-Access | AuthorizedClient, Service |
| Write-Access | No! (readonly) |
| Bool | |
| Value Range | False, True |
| Initialisation | False |

Variable Telegram Syntax

Read Variable:

sRN io1state

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | io1state | String | 8 | State of IO 1 |

Read Variable Response:

sRA io1state <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------|--------|---------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | io1state | String | 8 | State of IO 1 |
| Variable Data | data | Bool | 1 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|-------------------------|--------------------------|
| Read Variable: | [STX]sRN io1state[ETX] |
| Read Variable Response: | [STX]sRA io1state 0[ETX] |

3.3.1.7 Variable: io2state [bit 7 of status word: status (=switching state) of Q2]

The following section contains a detailed description of the variable io2state.

Variable Overview

| Variable Name | Description |
|----------------|---------------------------|
| io2state | State of IO 2 |
| Read-Access | AuthorizedClient, Service |
| Write-Access | No! (readonly) |
| Bool | |
| Value Range | False, True |
| Initialisation | False |

Variable Telegram Syntax

Read Variable:

sRN io2state

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | io2state | String | 8 | State of IO 2 |

| Read Variable Response: | | | | |
|--------------------------------|-----------------|-------------|----------------------|---------------------------------|
| sRA io2state <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | io2state | String | 8 | State of IO 2 |
| Variable Data | data | Bool | 1 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|--------------------------------|--------------------------|
| Read Variable: | [STX]sRN io2state[ETX] |
| Read Variable Response: | [STX]sRA io2state 0[ETX] |

3.3.1.8 Variable: io3state [bit 8 of status word: status (=switching state) of Q3]

The following section contains a detailed description of the variable io3state.

Variable Overview

| Variable Name | Description |
|----------------------|---------------------------|
| io3state | State of IO 3 |
| Read-Access | |
| Read-Access | AuthorizedClient, Service |
| Write-Access | |
| Write-Access | No! (readonly) |
| Bool | |
| Value Range | False, True |
| Initialisation | False |

Variable Telegram Syntax

Read Variable:

sRN io3state

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------|----------------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | io3state | String | 8 | State of IO 3 |

Read Variable Response:

sRA io3state <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------|----------------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | io3state | String | 8 | State of IO 3 |
| Variable Data | data | Bool | 1 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|--------------------------------|--------------------------|
| Read Variable: | [STX]sRN io3state[ETX] |
| Read Variable Response: | [STX]sRA io3state 0[ETX] |

3.3.1.9 Variable: io4state [bit 9 of status word: status (=switching state) of Q4]

The following section contains a detailed description of the variable io4state.

Variable Overview

| Variable Name | Description |
|----------------------|---------------------------|
| io4state | State of IO 4 |
| Read-Access | |
| Read-Access | AuthorizedClient, Service |
| Write-Access | |
| Write-Access | No! (readonly) |

| Bool | |
|----------------|-------------|
| Value Range | False, True |
| Initialisation | False |

Variable Telegram Syntax

Read Variable:

sRN io4state

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------|----------------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | io4state | String | 8 | State of IO 4 |

Read Variable Response:

sRA io4state <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------|----------------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | io4state | String | 8 | State of IO 4 |
| Variable Data | data | Bool | 1 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

Read Variable: [STX]sRN io4state[ETX]

Read Variable Response: [STX]sRA io4state 0[ETX]

3.3.1.10 Variable: io5state [bit 10 of status word: status (= input state) of In2]

The following section contains a detailed description of the variable io5state.

Variable Overview

| Variable Name | Description |
|----------------------|---------------------------|
| io5state | State of IO 5 |
| Read-Access | AuthorizedClient, Service |
| Write-Access | No! (readonly) |

Bool

Value Range

False, True

Initialisation

False

Variable Telegram Syntax

Read Variable:

sRN io5state

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------|----------------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | io5state | String | 8 | State of IO 5 |

Read Variable Response:

sRA io5state <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------|----------------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | io5state | String | 8 | State of IO 5 |
| Variable Data | data | Bool | 1 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

Read Variable: [STX]sRN io5state[ETX]

Read Variable Response: [STX]sRA io5state 0[ETX]

3.3.1.11 Variable: io1level [bit 1 of status word: level (= output or input potential) of Q1/In1]

The following section contains a detailed description of the variable io1level.

Variable Overview

| Variable Name | Description |
|----------------|---------------------------|
| io1level | State of IO 1 |
| Read-Access | AuthorizedClient, Service |
| Write-Access | No! (readonly) |
| Bool | |
| Value Range | False, True |
| Initialisation | False |

Variable Telegram Syntax

Read Variable:

sRN io1level

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | io1level | String | 8 | State of IO 1 |

Read Variable Response:

sRA io1level <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------|--------|---------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | io1level | String | 8 | State of IO 1 |
| Variable Data | data | Bool | 1 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|-------------------------|--------------------------|
| Read Variable: | [STX]sRN io1level[ETX] |
| Read Variable Response: | [STX]sRA io1level 0[ETX] |

3.3.1.12 Variable: io2level [bit 2 of status word: level (= output potential) of Q2]

The following section contains a detailed description of the variable io2level.

Variable Overview

| Variable Name | Description |
|----------------|---------------------------|
| io2level | Level of IO 2 |
| Read-Access | AuthorizedClient, Service |
| Write-Access | No! (readonly) |
| Bool | |
| Value Range | False, True |
| Initialisation | False |

Variable Telegram Syntax

Read Variable:

sRN io2level

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|----------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | io2level | String | 8 | Level of IO 2 |

| Read Variable Response: | | | | |
|--------------------------------|-----------------|-------------|----------------------|---------------------------------|
| sRA io2level <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | io2level | String | 8 | Level of IO 2 |
| Variable Data | data | Bool | 1 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|--------------------------------|--------------------------|
| Read Variable: | [STX]sRN io2level[ETX] |
| Read Variable Response: | [STX]sRA io2level 0[ETX] |

3.3.1.13 Variable: io3level [bit 3 of status word: level (= output potential) of Q3]

The following section contains a detailed description of the variable io3level.

Variable Overview

| Variable Name | Description |
|----------------------|---------------------------|
| io3level | Level of IO 3 |
| Read-Access | AuthorizedClient, Service |
| Write-Access | No! (readonly) |
| Bool | |
| Value Range | False, True |
| Initialisation | False |

Variable Telegram Syntax

Read Variable:

sRN io3level

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------|----------------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | io3level | String | 8 | Level of IO 3 |

Read Variable Response:

sRA io3level <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------|----------------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | io3level | String | 8 | Level of IO 3 |
| Variable Data | data | Bool | 1 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|--------------------------------|--------------------------|
| Read Variable: | [STX]sRN io3level[ETX] |
| Read Variable Response: | [STX]sRA io3level 0[ETX] |

3.3.1.14 Variable: io4level [bit 4 of status word: level (= output potential) of Q4]

The following section contains a detailed description of the variable io4level.

Variable Overview

| Variable Name | Description |
|----------------------|---------------------------|
| io4level | Level of IO 4 |
| Read-Access | AuthorizedClient, Service |
| Write-Access | No! (readonly) |

| Bool | |
|----------------|-------------|
| Value Range | False, True |
| Initialisation | False |

Variable Telegram Syntax

Read Variable:

sRN io4level

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------|----------------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | io4level | String | 8 | Level of IO 4 |

Read Variable Response:

sRA io4level <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------|----------------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | io4level | String | 8 | Level of IO 4 |
| Variable Data | data | Bool | 1 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

Read Variable: [STX]sRN io4level[ETX]

Read Variable Response: [STX]sRA io4level 0[ETX]

3.3.1.15 Variable: io5level [bit 5 of status word: level (= input potential) of In2]

The following section contains a detailed description of the variable io5level.

Variable Overview

| Variable Name | Description |
|----------------------|---------------------------|
| io5level | Level of IO 5 |
| Read-Access | AuthorizedClient, Service |
| Write-Access | No! (readonly) |

Bool

Value Range

False, True

Initialisation

False

Variable Telegram Syntax

Read Variable:

sRN io5level

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------|----------------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | io5level | String | 8 | Level of IO 5 |

Read Variable Response:

sRA io5level <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------|----------------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | io5level | String | 8 | Level of IO 5 |
| Variable Data | data | Bool | 1 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

Read Variable: [STX]sRN io5level[ETX]

Read Variable Response: [STX]sRA io5level 0[ETX]

3.3.1.16 Variable: deviceStatusWord [device status word definition]

The following section contains a detailed description of the variable deviceStatusWord.

Variable Overview

| Variable Name | Description |
|------------------|--------------------|
| deviceStatusWord | Device Status Word |
| Read-Access | Always |
| Write-Access | No! (readonly) |
| UDInt | |
| Value Range | 0..4294967295 |

Variable Telegram Syntax

| Read Variable: | | | | |
|--------------------------------|------------------|--------|---------------|---------------------------------|
| sRN deviceStatusWord | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | deviceStatusWord | String | 16 | Device Status Word |
| Read Variable Response: | | | | |
| sRA deviceStatusWord <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | deviceStatusWord | String | 16 | Device Status Word |
| Variable Data | data | UDInt | 4 | |

Variable Telegram Examples

| Example: Default Values | |
|---|----------------------------------|
| Variable telegram examples with data set to default values. | |
| Read Variable: | [STX] sRN deviceStatusWord[ETX] |
| Read Variable Response: | [STX]sRA deviceStatusWord 0[ETX] |

3.3.2 Error and Warning

3.3.2.1 Variable: laserError [bit 31 of status word: laser error]

The following section contains a detailed description of the variable laserError.

Variable Overview

| Variable Name | Description |
|----------------|---------------------------|
| laserError | Laser Error |
| Read-Access | AuthorizedClient, Service |
| Write-Access | No! (readonly) |
| Bool | |
| Value Range | False, True |
| Initialisation | False |

Variable Telegram Syntax

| Read Variable: | | | | |
|-----------------------|------------|--------|---------------|-----------------------------|
| sRN laserError | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | laserError | String | 10 | Laser Error |

| Read Variable Response: | | | | |
|--------------------------------|-----------------|-------------|----------------------|---------------------------------|
| sRA laserError <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | laserError | String | 10 | Laser Error |
| Variable Data | data | Bool | 1 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|--------------------------------|----------------------------|
| Read Variable: | [STX]sRN_laserError[ETX] |
| Read Variable Response: | [STX]sRA_laserError 0[ETX] |

3.3.2.2 Variable: hardwareFailure [bit 30 of status word: hardware error]

The following section contains a detailed description of the variable hardwareFailure.

Variable Overview

| Variable Name | Description |
|----------------------|---------------------------|
| hardwareFailure | Hardware Failure |
| Read-Access | AuthorizedClient, Service |
| Write-Access | No! (readonly) |
| Bool | |
| Value Range | False, True |
| Initialisation | False |

Variable Telegram Syntax

Read Variable:

sRN hardwareFailure

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------|----------------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | hardwareFailure | String | 15 | Hardware Failure |

Read Variable Response:

sRA hardwareFailure <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-----------------|-------------|----------------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | hardwareFailure | String | 15 | Hardware Failure |
| Variable Data | data | Bool | 1 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|--------------------------------|---------------------------------|
| Read Variable: | [STX]sRN_hardwareFailure[ETX] |
| Read Variable Response: | [STX]sRA_hardwareFailure 0[ETX] |

3.3.2.3 Variable: measurementError [bit 29 of status word: measurement error]

The following section contains a detailed description of the variable measurementError.

Variable Overview

| Variable Name | Description |
|----------------------|---------------------------|
| measurementError | Measurement Error |
| Read-Access | AuthorizedClient, Service |
| Write-Access | No! (readonly) |

| Bool | |
|----------------|-------------|
| Value Range | False, True |
| Initialisation | False |

Variable Telegram Syntax

Read Variable:

sRN measurementError

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|------------------|-------------|----------------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | measurementError | String | 16 | Measurement Error |

Read Variable Response:

sRA measurementError <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|------------------|-------------|----------------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | measurementError | String | 16 | Measurement Error |
| Variable Data | data | Bool | 1 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

Read Variable: [STX]sRN measurementError[ETX]

Read Variable Response: [STX]sRA measurementError 0[ETX]

3.3.2.4 Variable: ambientLightError [bit 27 of status word: ambient light error]

The following section contains a detailed description of the variable ambientLightError.

Variable Overview

| Variable Name | Description |
|----------------------|---------------------|
| ambientLightError | Ambient Light Error |

| | |
|--------------|---------------------------|
| Read-Access | AuthorizedClient, Service |
| Write-Access | No! (readonly) |

Bool

| | |
|----------------|-------------|
| Value Range | False, True |
| Initialisation | False |

Variable Telegram Syntax

Read Variable:

sRN ambientLightError

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-------------------|-------------|----------------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | ambientLightError | String | 17 | Ambient Light Error |

Read Variable Response:

sRA ambientLightError <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|-------------------|-------------|----------------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | ambientLightError | String | 17 | Ambient Light Error |
| Variable Data | data | Bool | 1 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

Read Variable: [STX]sRN ambientLightError[ETX]

Read Variable Response: [STX]sRA ambientLightError 0[ETX]

3.3.2.5 Variable: temperatureError [bit 28 of status word: temperature error]

The following section contains a detailed description of the variable temperatureError.

Variable Overview

| Variable Name | Description |
|------------------|---------------------------|
| temperatureError | Laser Error |
| Read-Access | AuthorizedClient, Service |
| Write-Access | No! (readonly) |
| Bool | |
| Value Range | False, True |
| Initialisation | False |

Variable Telegram Syntax

Read Variable:

sRN temperatureError

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|------------------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | temperatureError | String | 16 | Laser Error |

Read Variable Response:

sRA temperatureError <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|------------------|--------|---------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | temperatureError | String | 16 | Laser Error |
| Variable Data | data | Bool | 1 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

Read Variable: [STX] sRN temperatureError [ETX]

Read Variable Response: [STX] sRA temperatureError 0 [ETX]

3.3.2.6 Variable: laserWarning [bit 23 of status word: warning: Laser]

The following section contains a detailed description of the variable laserWarning.

Variable Overview

| Variable Name | Description |
|----------------|---------------------------|
| laserWarning | Laser Warning |
| Read-Access | AuthorizedClient, Service |
| Write-Access | No! (readonly) |
| Bool | |
| Value Range | False, True |
| Initialisation | False |

Variable Telegram Syntax

Read Variable:

sRN laserWarning

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|--------------|--------|---------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | laserWarning | String | 12 | Laser Warning |

| Read Variable Response: | | | | |
|--------------------------------|-----------------|-------------|----------------------|---------------------------------|
| sRA laserWarning <data> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | laserWarning | String | 12 | Laser Warning |
| Variable Data | data | Bool | 1 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|--------------------------------|------------------------------|
| Read Variable: | [STX]sRN_laserWarning[ETX] |
| Read Variable Response: | [STX]sRA_laserWarning_0[ETX] |

3.3.2.7 Variable: firmwareWarning [bit 22 of status word: firmware warning]

The following section contains a detailed description of the variable `firmwareWarning`.

Variable Overview

| Variable Name | Description |
|----------------------|---------------------------|
| firmwareWarning | Firmware Warning |
| Read-Access | AuthorizedClient, Service |
| Write-Access | No! (readonly) |
| Bool | |
| Value Range | False, True |
| Initialisation | False |

Variable Telegram Syntax

| | | | | |
|--------------------------------|---------------------------------|--|--|--|
| Read Variable: | sRN_firmwareWarning | | | |
| Read Variable Response: | | | | |
| Read Variable: | [STX]sRN_firmwareWarning[ETX] | | | |
| Read Variable Response: | [STX]sRA_firmwareWarning_0[ETX] | | | |
| Read Variable: | | | | |
| Read Variable Response: | [STX]sRN_firmwareWarning[ETX] | | | |
| Read Variable: | [STX]sRN_firmwareWarning[ETX] | | | |
| Read Variable Response: | [STX]sRA_firmwareWarning_0[ETX] | | | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

| | |
|--------------------------------|---------------------------------|
| Read Variable: | [STX]sRN_firmwareWarning[ETX] |
| Read Variable Response: | [STX]sRA_firmwareWarning_0[ETX] |

3.3.2.8 Variable: ambientLightWarning [bit 19 of status word: warning: ambient light]

The following section contains a detailed description of the variable `ambientLightWarning`.

Variable Overview

| Variable Name | Description |
|----------------------|---------------------------|
| ambientLightWarning | Ambient Light Warning |
| Read-Access | AuthorizedClient, Service |
| Write-Access | No! (readonly) |

| Bool | |
|----------------|-------------|
| Value Range | False, True |
| Initialisation | False |

Variable Telegram Syntax

Read Variable:

sRN ambientLightWarning

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|---------------------|-------------|----------------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | ambientLightWarning | String | 19 | Ambient Light Warning |

Read Variable Response:

sRA ambientLightWarning <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|---------------------|-------------|----------------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | ambientLightWarning | String | 19 | Ambient Light Warning |
| Variable Data | data | Bool | 1 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

Read Variable: [STX]sRN ambientLightWarning[ETX]

Read Variable Response: [STX]sRA ambientLightWarning 0[ETX]

3.3.2.9 Variable: temperatureWarning [bit 20 of status word: warning: temperature]

The following section contains a detailed description of the variable temperatureWarning.

Variable Overview

| Variable Name | Description |
|----------------------|--------------------|
| temperatureWarning | Laser Warning |

| | |
|--------------|---------------------------|
| Read-Access | AuthorizedClient, Service |
| Write-Access | No! (readonly) |

Bool

| | |
|----------------|-------------|
| Value Range | False, True |
| Initialisation | False |

Variable Telegram Syntax

Read Variable:

sRN temperatureWarning

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|--------------------|-------------|----------------------|-----------------------------|
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | temperatureWarning | String | 18 | Laser Warning |

Read Variable Response:

sRA temperatureWarning <data>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------------|--------------------|-------------|----------------------|---------------------------------|
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | temperatureWarning | String | 18 | Laser Warning |
| Variable Data | data | Bool | 1 | |

Variable Telegram Examples

Example: Default Values

Variable telegram examples with data set to default values.

Read Variable: [STX]sRN temperatureWarning[ETX]

Read Variable Response: [STX]sRA temperatureWarning 0[ETX]

3.3.2.10 Variable: doFault [bit 21 of status word: warning: shortcircuit at switching output]

The following section contains a detailed description of the variable doFault.

Variable Overview

| Variable Name | Description |
|---------------|------------------------|
| doFault | Fault at DO 1,2,3 or 4 |

| | |
|--------------|---------------------------|
| Read-Access | AuthorizedClient, Service |
| Write-Access | No! (readonly) |

| Bool | |
|----------------|-------------|
| Value Range | False, True |
| Initialisation | False |

Variable Telegram Syntax

| Read Variable: | | | | |
|----------------|----------|--------|---------------|-----------------------------|
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRN | String | 3 | Read SOPAS Variable by Name |
| Command | doFault | String | 7 | Fault at DO 1,2,3 or 4 |

| Read Variable Response: | | | | |
|-------------------------|----------|--------|---------------|---------------------------------|
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sRA | String | 3 | SOPAS Variable Read Acknowledge |
| Command | doFault | String | 7 | Fault at DO 1,2,3 or 4 |
| Variable Data | data | Bool | 1 | |

Variable Telegram Examples

| Example: Default Values | |
|---|-------------------------|
| Variable telegram examples with data set to default values. | |
| Read Variable: | [STX]sRN doFault[ETX] |
| Read Variable Response: | [STX]sRA doFault 0[ETX] |

3.4 Methods

3.4.1 General

3.4.1.1 Method: SetAccessMode

The following section contains a detailed description of the method SetAccessMode.

Method Overview

| Method Name | Description |
|-------------------|---|
| SetAccessMode | Change operation mode returns True, if successful |
| Invocation Access | |
| Invocation Access | Always |
| Parameters | |
| NewMode | |
| SInt | |
| Value Range | -128..127 |
| Password | hash value |
| UDInt | |
| Value Range | 0..4294967295 |

| Return Values | |
|----------------------|-------------|
| success | |
| Bool | |
| Value Range | False, True |
| Initialisation | False |

Method Telegram Syntax

| Method Invocation: | | | | |
|--|-----------------|-------------|----------------------|---|
| sMN SetAccessMode <NewMode> <Password> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sMN | String | 3 | Request (SOPAS Method by Name) |
| Command | SetAccessMode | String | 13 | Change operation mode returns True, if successful |
| Parameter 1 | NewMode | SInt | 1 | |
| Parameter 2 | Password | UDInt | 4 | hash value |

| Method Return Value: | | | | |
|-----------------------------|-----------------|-------------|----------------------|---|
| sAN SetAccessMode <success> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sAN | String | 3 | Result (SOPAS Method Result) |
| Command | SetAccessMode | String | 13 | Change operation mode returns True, if successful |
| Return Value 1 | success | Bool | 1 | |

| Example: Default Values | | | | |
|---|-----------------------------------|--|--|--|
| Method telegram examples with parameter data and return value data set to default values. | | | | |
| Method Invocation: | [STX] sMN SetAccessMode 0 0 [ETX] | | | |
| Method Return Value: | [STX] sAN SetAccessMode 0 [ETX] | | | |

3.4.1.2 Method: Run

The following section contains a detailed description of the method Run.

Method Overview

| Method Name | Description |
|--------------------------|--------------------------------|
| Run | Change operation mode to "Run" |
| Invocation Access | |
| Invocation Access | Always |
| Return Values | |
| success | |
| Bool | |
| Value Range | False, True |
| Initialisation | False |

Method Telegram Syntax

| Method Invocation: | | | | |
|-----------------------------|-----------------|-------------|----------------------|--------------------------------|
| sMN Run | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sMN | String | 3 | Request (SOPAS Method by Name) |
| Command | Run | String | 3 | Change operation mode to "Run" |
| Method Return Value: | | | | |
| sAN Run <success> | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sAN | String | 3 | Result (SOPAS Method Result) |
| Command | Run | String | 3 | Change operation mode to "Run" |
| Return Value 1 | success | Bool | 1 | |

Example: Default Values

Method telegram examples with parameter data and return value data set to default values.

| | |
|-----------------------------|----------------------|
| Method Invocation: | [STX]sMN Run [ETX] |
| Method Return Value: | [STX]sAN Run 0 [ETX] |

3.4.1.3 Method: resetParamAndReboot [reset and reboot]

The following section contains a detailed description of the method resetParamAndReboot.

Method Overview

| Method Name | Description |
|----------------------|--------------------------------------|
| resetParamAndReboot | reset the parametrization and reboot |
| Invocation Access | AuthorizedClient, Service |
| Return Values | |
| Successful | |
| Bool | |
| Value Range | False, True |
| Initialisation | False |

Method Telegram Syntax**Method Invocation:**

sMN resetParamAndReboot

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|---------------------|--------|---------------|--------------------------------------|
| Command Type | sMN | String | 3 | Request (SOPAS Method by Name) |
| Command | resetParamAndReboot | String | 19 | reset the parametrization and reboot |

Method Return Value:

sAN resetParamAndReboot <Successful>

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|----------------|---------------------|--------|---------------|--------------------------------------|
| Command Type | sAN | String | 3 | Result (SOPAS Method Result) |
| Command | resetParamAndReboot | String | 19 | reset the parametrization and reboot |
| Return Value 1 | Successful | Bool | 1 | |

Example: Default Values

Method telegram examples with parameter data and return value data set to default values.

| | |
|-----------------------------|--------------------------------------|
| Method Invocation: | [STX]sMN resetParamAndReboot [ETX] |
| Method Return Value: | [STX]sAN resetParamAndReboot 0 [ETX] |

3.4.1.4 Method: RebootDevice [reboot]

The following section contains a detailed description of the method RebootDevice.

Method Overview

| Method Name | Description |
|--------------------|---|
| RebootDevice | Method shuts the device down but saves the parameter before shutdown ist executed |
| Communication Name | mSCreboot |
| Invocation Access | AuthorizedClient, Service |

Method Telegram Syntax**Method Invocation:**

sMN mSCreboot

| Telegram Part | Telegram | Type | Length [Byte] | Description |
|---------------|-----------|--------|---------------|---|
| Command Type | sMN | String | 3 | Request (SOPAS Method by Name) |
| Command | mSCreboot | String | 9 | Method shuts the device down but saves the parameter before shutdown ist executed |

| Method Return Value: | | | | |
|-----------------------------|-----------------|-------------|----------------------|---|
| sAN mSCreboot | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sAN | String | 3 | Result (SOPAS Method Result) |
| Command | mSCreboot | String | 9 | Method shuts the device down but saves the parameter before shutdown ist executed |

Method Telegram Examples

| Example: Default Values | |
|---|---------------------------|
| Method telegram examples with parameter data and return value data set to default values. | |
| Method Invocation: | [STX] sMN mSCreboot [ETX] |
| Method Return Value: | [STX] sAN mSCreboot [ETX] |

3.4.2 Preset

3.4.2.1 Method: autoZero [set output to 0]

The following section contains a detailed description of the method autoZero.

Method Overview

| Method Name | Description |
|--------------------|---------------------------|
| autoZero | Auto Zero |
| Invocation Access | AuthorizedClient, Service |

Method Telegram Syntax

| Method Invocation: | |
|-----------------------------|-----------------|
| sMN autoZero | |
| Telegram Part | Telegram |
| Command Type | sMN |
| Command | autoZero |
| Method Return Value: | |
| sAN autoZero | |
| Telegram Part | Telegram |
| Command Type | sAN |
| Command | autoZero |

Method Telegram Examples

| Example: Default Values | |
|---|--------------------------|
| Method telegram examples with parameter data and return value data set to default values. | |
| Method Invocation: | [STX] sMN autoZero [ETX] |
| Method Return Value: | [STX] sAN autoZero [ETX] |

3.4.2.2 Method: activatePreset [activate preset]

The following section contains a detailed description of the method activatePreset.

Method Overview

| Method Name | Description |
|--------------------|---------------------------|
| activatePreset | Activate preset |
| Invocation Access | AuthorizedClient, Service |

Method Telegram Syntax

| Method Invocation: | |
|---------------------------|-----------------|
| sMN activatePreset | |
| Telegram Part | Telegram |
| Command Type | sMN |
| Command | activatePreset |

| Method Return Value: | | | | |
|-----------------------------|-----------------|-------------|----------------------|------------------------------|
| sAN activatePreset | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sAN | String | 3 | Result (SOPAS Method Result) |
| Command | activatePreset | String | 14 | Activate preset |

Method Telegram Examples

Example: Default Values

Method telegram examples with parameter data and return value data set to default values.

| | |
|-----------------------------|------------------------------|
| Method Invocation: | [STX]sMN activatePreset[ETX] |
| Method Return Value: | [STX]sAN activatePreset[ETX] |

3.4.2.3 Method: resetPreset [delete preset value]

The following section contains a detailed description of the method resetPreset.

Method Overview

| Method Name | Description |
|--------------------|---------------------------|
| resetPreset | Reset any pending preset |
| Invocation Access | AuthorizedClient, Service |

Method Telegram Syntax

| Method Invocation: | | | | |
|-----------------------------|-----------------|-------------|----------------------|--------------------------------|
| sMN resetPreset | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sMN | String | 3 | Request (SOPAS Method by Name) |
| Command | resetPreset | String | 11 | Reset any pending preset |
| Method Return Value: | | | | |
| sAN resetPreset | | | | |
| Telegram Part | Telegram | Type | Length [Byte] | Description |
| Command Type | sAN | String | 3 | Result (SOPAS Method Result) |
| Command | resetPreset | String | 11 | Reset any pending preset |

Method Telegram Examples

Example: Default Values

Method telegram examples with parameter data and return value data set to default values.

| | |
|-----------------------------|---------------------------|
| Method Invocation: | [STX]sMN resetPreset[ETX] |
| Method Return Value: | [STX]sAN resetPreset[ETX] |

4 User Types

4.1 IOs

4.1.1 Type: ioConfiguration_t

The following section contains a detailed description of the user type ioConfiguration_t.

| Type | Description |
|---------------------|---|
| ioConfiguration_t | Configuration options for an IO |
| Struct | |
| doFunction | |
| UserType | |
| doFunction_t | See the chapter "User Types" for details. |
| doDistFunction | |
| UserType | |
| distanceFunction_t | See the chapter "User Types" for details. |
| doVeloFunction | |
| UserType | |
| movementDirection_t | See the chapter "User Types" for details. |
| diFunction | |
| UserType | |
| diFunction_t | See the chapter "User Types" for details. |
| lowerPoint | |
| UserType | |
| lowerSwitchPoint_t | See the chapter "User Types" for details. |
| upperPoint | |
| UserType | |
| upperSwitchPoint_t | See the chapter "User Types" for details. |
| distHysteresis | |
| UserType | |
| distHysteresis_t | See the chapter "User Types" for details. |
| veloSwitchpoint | |
| UserType | |
| veloSwitchpoint_t | See the chapter "User Types" for details. |
| veloHysteresis | |
| UserType | |
| veloHysteresis_t | See the chapter "User Types" for details. |
| servFuncSelection | |
| UserType | |
| serviceFunction_t | See the chapter "User Types" for details. |
| activeState | |
| UserType | |
| activeState_t | See the chapter "User Types" for details. |

4.1.2 Type: doFunction_t [assign monitoring function (distance, object speed or service) to digital output]

The following section contains a detailed description of the user type doFunction_t.

| Type | Description |
|--------------|-------------|
| doFunction_t | DO Function |

| Enum8 | | | |
|---------------|----------|-------------|--|
| Default Value | DISTANCE | | |
| Value | Name | Description | |
| 0 | DISTANCE | | |
| 1 | VELOCITY | | |
| 2 | SERVICE | | |

4.1.3 Type: distanceFunction_t [define switching function]

The following section contains a detailed description of the user type distanceFunction_t.

| Type | Description |
|--------------------|-------------------|
| distanceFunction_t | Distance Function |

| Enum8 | | | |
|---------------|--------|-------------|--|
| Default Value | DTO | | |
| Value | Name | Description | |
| 0 | DTO | | |
| 1 | WINDOW | | |
| 2 | OBSB | | |

4.1.4 Type: movementDirection_t [defining the monitoring direction for the object speed value: positive (+) or Negative (-) or positive and negative (+/-)]

The following section contains a detailed description of the user type movementDirection_t.

| Type | Description |
|---------------------|--|
| movementDirection_t | selects the movement directions which are controlled |

| Enum8 | | | |
|---------------|--------------------|--------------------------------|--|
| Default Value | BOTH | | |
| Value | Name | Description | |
| 0 | POSITIVE_DIRECTION | distance value is increasing | |
| 1 | NEGATIVE_DIRECTION | distance values decreasing | |
| 2 | BOTH | both directions are controlled | |

4.1.5 Type: diFunction_t [configuring the switching input: preset, alignment laser on, measurement laser off, deactivated]

The following section contains a detailed description of the user type diFunction_t.

| Type | Description |
|--------------|-------------|
| diFunction_t | DI Function |

| Enum8 | | | |
|---------------|----------------|-------------|--|
| Default Value | NO_FUNCTION | | |
| Value | Name | Description | |
| 0 | PRESET_TRIGGER | | |
| 1 | PILOT_ON | | |
| 2 | LASER_OFF | | |
| 3 | NO_FUNCTION | | |

4.1.6 Type: lowerSwitchPoint_t [switching function "distance to object": defining the switching point SP for distance value. Switching function "window": switching pointSP1]

The following section contains a detailed description of the user type lowerSwitchPoint_t.

| Type | Description |
|--------------------|--|
| lowerSwitchPoint_t | Point 1 (Can be Switch Point or 4mA point) |

| DInt | |
|----------------|-------------------|
| Value Range | -4500000..4500000 |
| Initialisation | 10000 |

4.1.7 Type: upperSwitchPoint_t [switching function "distance to object": NOT USED. Switching function "window": switching point SP2]

The following section contains a detailed description of the user type upperSwitchPoint_t.

| Type | Description |
|--------------------|---|
| upperSwitchPoint_t | Point 2 (Can be Switch Point or 20mA point) |

| DInt | |
|----------------|-------------------|
| Value Range | -4500000..4500000 |
| Initialisation | 20000 |

4.1.8 Type: distHysteresis_t [switching hysteresis for the distance value]

The following section contains a detailed description of the user type distHysteresis_t.

| Type | Description |
|------------------|------------------|
| distHysteresis_t | Hysteresis in mm |

| UDInt | |
|----------------|------------|
| Value Range | 0..1500000 |
| Initialisation | 100 |

4.1.9 Type: veloSwitchpoint_t [switching point for the object speed value]

The following section contains a detailed description of the user type veloSwitchpoint_t.

| Type | Description |
|-------------------|-------------------------------|
| veloSwitchpoint_t | Velocity switch point in mm/s |

| UDInt | |
|----------------|----------|
| Value Range | 0..20000 |
| Initialisation | 5000 |

4.1.10 Type: veloHysteresis_t [switching point hysteresis for the object speed value]

The following section contains a detailed description of the user type veloHysteresis_t.

| Type | Description |
|------------------|-------------------------------|
| veloHysteresis_t | Velocity switch point in mm/s |

| UDInt | |
|----------------|---------|
| Value Range | 0..1000 |
| Initialisation | 50 |

4.1.11 Type: activeState_t [defining the active state]

The following section contains a detailed description of the user type activeState_t.

| Type | Description |
|---------------|-----------------------------------|
| activeState_t | I/O pin can be high or low active |

| Enum8 | | | |
|---------------|-------|-------------|--|
| Default Value | | Description | |
| | Value | Name | |
| | 0 | HIGH_ACTIVE | |
| | 1 | LOW_ACTIVE | |

4.1.12 Type: serviceFunctionState_t [Assigning a switching event to the service functions]

The following section contains a detailed description of the user type serviceFunctionState_t.

| Type | Description |
|------------------------|---|
| serviceFunctionState_t | Service function can be en- or disabled |

| Enum8 | | | |
|---------------|-------|----------|-------------|
| Default Value | | Name | |
| | Value | Name | Description |
| | 0 | DISABLED | |
| | 1 | ENABLED | |

5 Appendix

5.1 Telegram structure: sFA ErrorCode

| Error code | Description | Dec. | Hex. |
|---|---|------|------|
| Sopas_Ok | No error | 0 | 0 |
| Sopas_Error_METHODIN_ACCESSDENIED | Wrong userlevel, access to method not allowed | 1 | 1 |
| Sopas_Error_METHODIN_UNKNOWNINDEX | Trying to access a method with an unknown Sopas index | 2 | 2 |
| Sopas_Error_VARIABLE_UNKNOWNINDEX | Trying to access a variable with an unknown Sopas index | 3 | 3 |
| Sopas_Error_LOCALCONDITIONFAILED | Local condition violated, e.g. giving a value that exceeds the minimum or maximum allowed value for this variable | 4 | 4 |
| Sopas_Error_INVALID_DATA | Invalid data given for variable, this errorcode is deprecated (is not used anymore). | 5 | 5 |
| Sopas_Error_UNKNOWN_ERROR | An error with unknown reason occurred, this errorcode is deprecated. | 6 | 6 |
| Sopas_Error_BUFFER_OVERFLOW | The communication buffer was too small for the amount of data that should be serialised. | 7 | 7 |
| Sopas_Error_BUFFER_UNDERFLOW | More data was expected, the allocated buffer could not be filled. | 8 | 8 |
| Sopas_Error_ERROR_UNKNOWN_TYPE | The variable that shall be serialised has an unknown type. This can only happen when there are variables in the firmware of the device that do not exist in the released description of the device. This should never happen. | 9 | 9 |
| Sopas_Error_VARIABLE_WRITE_ACCESSDENIED | It is not allowed to write values to this variable. Probably the variable is defined as read-only. | 10 | A |
| Sopas_Error_UNKNOWN_CMD_FOR_NAMERVER | When using names instead of indices, a command was issued that the nameserver does not understand. | 11 | B |
| Sopas_Error_UNKNOWN_COLA_COMMAND | The CoLa protocol specification does not define the given command, command is unknown. | 12 | C |
| Sopas_Error_METHODIN_SERVER_BUSY | It is not possible to issue more than one command at a time to an SRT device. | 13 | D |
| Sopas_Error_FLEX_OUT_OF_BOUNDS | An array was accessed over its maximum length. | 14 | E |
| Sopas_Error_EVENTREG_UNKNOWNINDEX | The event you wanted to register for does not exist, the index is unknown. | 15 | F |
| Sopas_Error_COLA_A_VALUE_OVERFLOW | The value does not fit into the value field, it is too large. | 16 | 10 |
| Sopas_Error_COLA_A_INVALID_CHARACTER | Character is unknown, probably not alphanumeric. | 17 | 11 |

| Error code | Description | Dec. | Hex. |
|---------------------------------------|---|------|------|
| Sopas_Error_OSAI_NO_MESSAGE | Only when using SRTOS in the firmware and distributed variables this error can occur. It is an indication that no operating system message could be created. This happens when trying to GET a variable. | 18 | 12 |
| Sopas_Error_OSAI_NO_ANSWER_MESSAGE | This is the same as Sopas_Error_OSAI_NO_MESSAGE with the difference that it is thrown when trying to PUT a variable. | 19 | 13 |
| Sopas_Error_INTERNAL | Internal error in the firmware, probably a pointer to a parameter was null. | 20 | 14 |
| Sopas_Error_HubAddressCorrupted | The Sopas Hubaddress is either too short or too long. | 21 | 15 |
| Sopas_Error_HubAddressDecoding | The Sopas Hubaddress is invalid, it can not be decoded (Syntax). | 22 | 16 |
| Sopas_Error_HubAddressAddressExceeded | Too many hubs in the address | 23 | 17 |
| Sopas_Error_HubAddressBlankExpected | When parsing a HubAddress an expected blank was not found. The HubAddress is not valid. | 24 | 18 |
| Sopas_Error_AsyncMethodsAreSuppressed | An asynchronous method call was made although the device was built with "AsyncMethodsSuppressed". This is an internal error that should never happen in a released device. | 25 | 19 |
| Sopas_Error_ComplexArraysNotSupported | Device was built with „ComplexArraysSuppressed“ because the compiler does not allow recursions. But now a complex array was found. This is an internal error that should never happen in a released device. | 26 | 20 |

Example: sFA ErrorCode Wrong userlevel

| | | |
|-------|-------|-------------------------|
| Col A | ASCII | <STX>sFA{SPC}01<ETX> |
| | Hex | 02 73 46 41 20 30 31 03 |

| | | |
|--|---|--|
| Australia Phone +61 3 9457 0600 1800 334 802 – tollfree E-Mail sales@sick.com.au | Israel Phone +972 4 6881000 E-Mail info@sick-sensors.com | South Korea Phone +82 2 786 6321 E-Mail info@sickkorea.net |
| Austria Phone +43 22 36 62 28 8-0 E-Mail office@sick.at | Italy Phone +39 02 274341 E-Mail info@sick.it | Spain Phone +34 93 480 31 00 E-Mail info@sick.es |
| Belgium/Luxembourg Phone +32 2 466 55 66 E-Mail info@sick.be | Japan Phone +81 3 5309 2112 E-Mail support@sick.jp | Sweden Phone +46 10 110 10 00 E-Mail info@sick.se |
| Brazil Phone +55 11 3215-4900 E-Mail marketing@sick.com.br | Malaysia Phone +6 03 8080 7425 E-Mail enquiry.my@sick.com | Switzerland Phone +41 41 619 29 39 E-Mail contact@sick.ch |
| Canada Phone +1 905 771 14 44 E-Mail information@sick.com | Mexico Phone +52 (472) 748 9451 E-Mail mario.garcia@sick.com | Taiwan Phone +886 2 2375-6288 E-Mail sales@sick.com.tw |
| Czech Republic Phone +420 2 57 91 18 50 E-Mail sick@sick.cz | Netherlands Phone +31 30 2044 0000 E-Mail info@sick.nl | Thailand Phone +66 2645 0009 E-Mail Ronnie.Lim@sick.com |
| Chile Phone +56 2 2274 7430 E-Mail info@schadler.com | New Zealand Phone +64 9 415 0459 0800 222 278 – tollfree E-Mail sales@sick.co.nz | Turkey Phone +90 216 528 50 00 E-Mail info@sick.com.tr |
| China Phone +86 20 2882 3600 E-Mail info.china@sick.netcn | Norway Phone +47 67 81 50 00 E-Mail sick@sick.no | United Arab Emirates Phone +971 4 88 65 878 E-Mail info@sick.ae |
| Denmark Phone +45 45 82 64 00 E-Mail sick@sick.dk | Poland Phone +48 22 539 41 00 E-Mail info@sick.pl | United Kingdom Phone +44 1727 831121 E-Mail info@sick.co.uk |
| Finland Phone +358-9-2515 800 E-Mail sick@sick.fi | Romania Phone +40 356 171 120 E-Mail office@sick.ro | USA Phone +1 800 325 7425 E-Mail info@sick.com |
| France Phone +33 1 64 62 35 00 E-Mail info@sick.fr | Singapore Phone +65 6744 3732 E-Mail sales.gsg@sick.com | Vietnam Phone +84 945452999 E-Mail Ngo.Duy.Linh@sick.com |
| Germany Phone +49 211 5301-301 E-Mail info@sick.de | Slovakia Phone +421 482 901201 E-Mail mail@sick-sk.sk | |
| Hong Kong Phone +852 2153 6300 E-Mail ghk@sick.com.hk | Slovenia Phone +386 591 788 49 E-Mail office@sick.si | |
| Hungary Phone +36 1 371 2680 E-Mail office@sick.hu | South Africa Phone +27 11 472 3733 E-Mail info@sickautomation.co.za | |
| India Phone +91 22 6119 8900 E-Mail info@sick-india.com | | Further locations at www.sick.com |